

# Inspectors Workshop Advanced Materials and Technology (AMT) Update

Wednesday, February 17 and Tuesday, February 23, 2021

Virtual via Teams



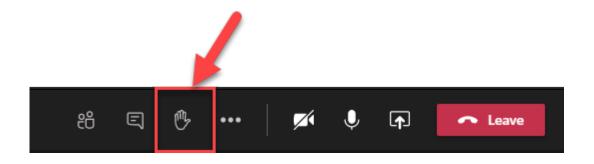
#### Discussions

#### • Slides

• Open to Discussion – Interactive

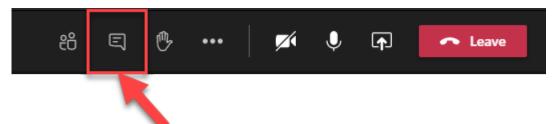
#### • Verbal Comments / Questions:

Raise Hand in Microsoft Teams



#### • Written Comments

• Chat Box





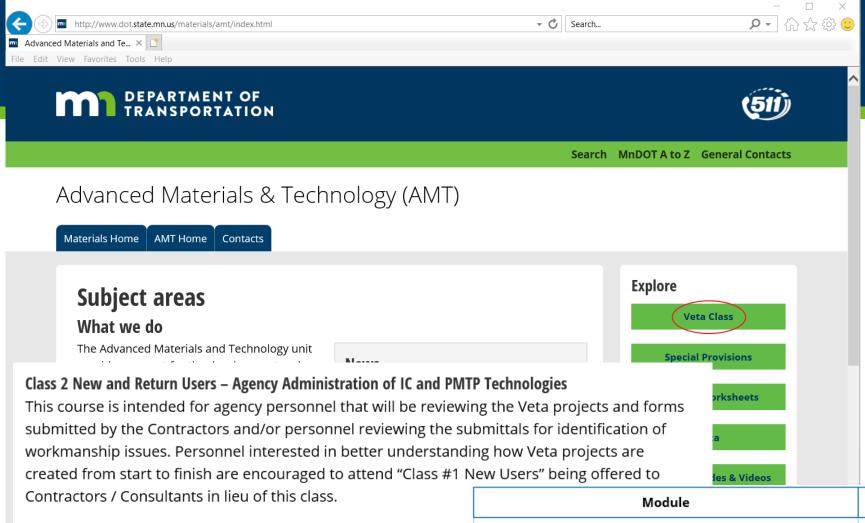
# (2016) Quality Management Intelligent Construction Technologies

Michael M Johnson
Assistant Advanced Materials and Technology Engineer

## Veta Training

- 2021
  - Not expiring users(Contractors)
  - Users (Contractors) that did not complete 2020 training and plan to create Veta and form submittals in CY2021 must take online class.
  - Agency (District) training will be provided in spring of 2022

- Significant Veta enhancements expected for 2022.
  - Anticipate expiring Users (Contractors) in 2022



Step 1 - Videos of PowerPoint Slides for Agency Administration

Step 2 - Instructions and Modules for Veta Class Project

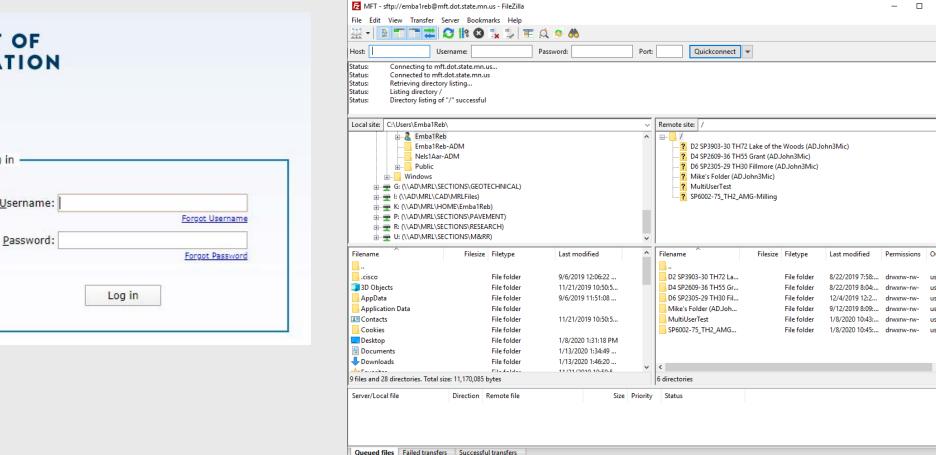
#### ICT-106 Form

Module	Links	New & Return Users
<b>Class Example</b> File Downloads	County/Consultants Contact AMT unit to obtain file downloads. MnDOT Download files from iHUB	✓
Module F Complete ICT-106 Form	Module F Video (9 minutes)  Module F Workflow (pdf)	✓

# File Sharing MnDOT MFT Site

Queue: empty

# <u>Larger File Uploads / Downloads:</u> Recommend using SFTP Platform (e.g., Filezilla)





### File Sharing on MnDOT MFT Site

Provide AMT unit with name and e-mail address of personnel requiring access to project folders in MFT site.

Not Long-Term Storage Non-Carry Over Projects – Deleting March 1



## General Special Provision Edits

- ADA Compliance
  - Removed Merged Cells in Tables
  - Removed symbols from general text body
  - Units written in long form (e.g., ft = feet)
  - Complex tables deleted and moved to body of text
    - "Required Instrumented Roller Equipment"
    - "PMTP System Requirements"
- Pay items to use ICT equipment moved from general section to section B "PMTP method" and C "IC Method"

## PMTP GNSS Accuracy

- S-xx.3.B.1.a(2)
  - GNSS to capture coordinates of the surface temperature readings. GNSS accuracy is <u>plus</u>
     <u>or minus 2 inches</u> or less in X and Y Directions.

- S-xx.5 Basis of Payment
  - Monetary Adjustments for GNSS Accuracy Deleted
    - A single lump sum payment of \$5,000 will be issued when the thermal profile measurements are collected with an associated GNSS accuracy of ± 2 inches in the X and Y direction.

## PMTP Method – Thermal Coverage (TC)

No changes to TC calculation (calculated using total linear length)

- Anticipated 2022 Changes:
  - Calculate per sublot
  - Review 70% TC threshold

## Veta Project and Form Submittals

added in fall of 2019 to the special provision...

- S-xx.3.A.1
  - A monetary deduction of \$500 per calendar day will be assessed for submitting the final version of the Veta Project(s) and required forms later than 14-calendar days of completion of the ICT method.

# Table 2016-11 Partial Payments Schedule

Added 75% Added Final Approval of Submittals (remaining 25%)

When	Percent of Estimated Quantity Completed	Pay Percent of Lump Sum Item
First Pay Estimate	(Blank)	10
Subsequent Pay Estimate *	5	15
Subsequent Pay Estimate *	15	30
Subsequent Pay Estimate *	50	50
Subsequent Pay Estimate *	75	75
Final Approval of Submittals	100	100

<sup>\*</sup> Percent of Estimated Quantity Completed is based on the pay quantity where the given ICT method is required:

2215.504 Stabilized Full Depth Reclamation

2390.504 CIR – CCPR Bituminous

2353.504 Ultrathin Bonded Wear Course

2360.509 Type SP Wearing Course Mixture

2360.509 Type SP Non-Wearing Course Mixture

2360.504 Type SP Wearing Course Mixture in [mm] Thick

2360.504 Type SP Non-Wearing Course Mixture in [mm] Thick

2365.509 Type SM Wearing Course Mixture



## S-xx.5 Basis of Payment New Pay Items

#### Contract Lump Sum

- 2016.601 Quality Management Thermal Profiling...... Lump Sum
- 2016.601 Quality Management Intelligent Compaction...... Lump Sum

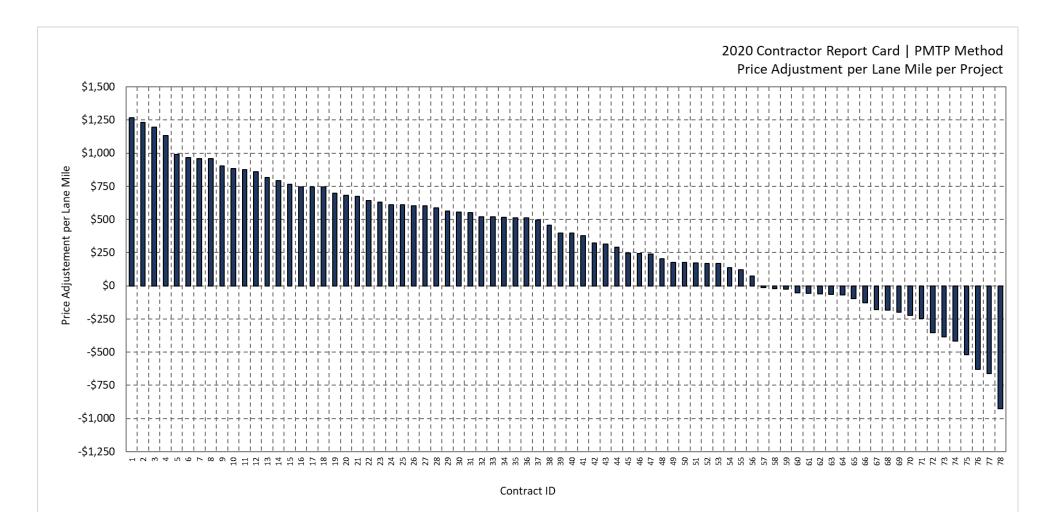
- Setup of cloud storage and computing
- Conversion of design files
- Site calibration
- Instrumentation of equipment with ICT system
- ICT system and software setup
- Equipment setup for satellite corrections
- Data lot establishment

- System monitoring
- Remote server storage
- Cloud-based software accessibility
- Data package plans
- Analysis and organization of ICT measurements in Veta
- Completion of ICT submittal forms

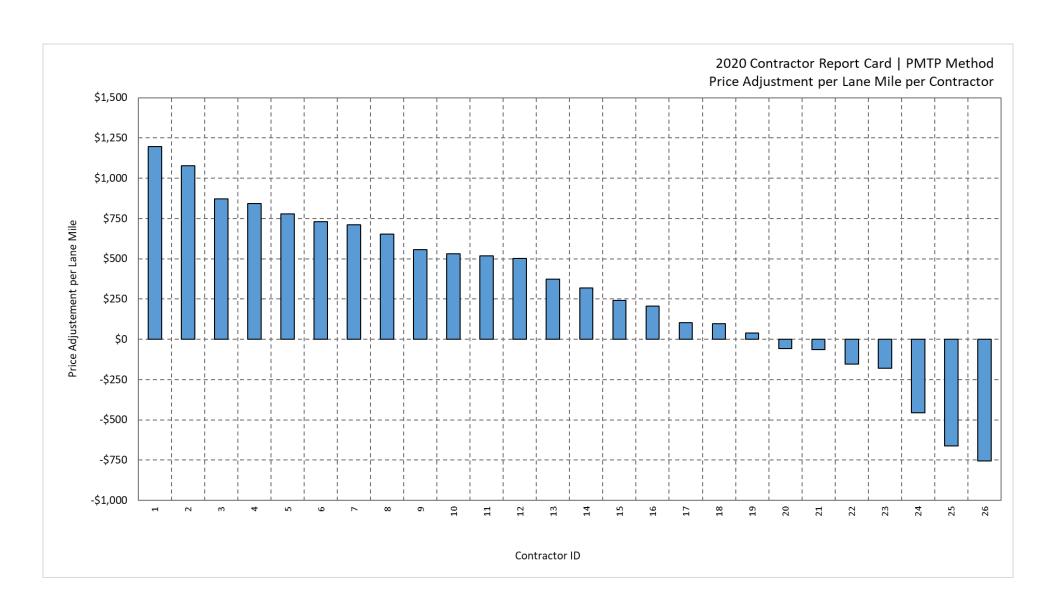
# (2016) Quality Management Report Cards



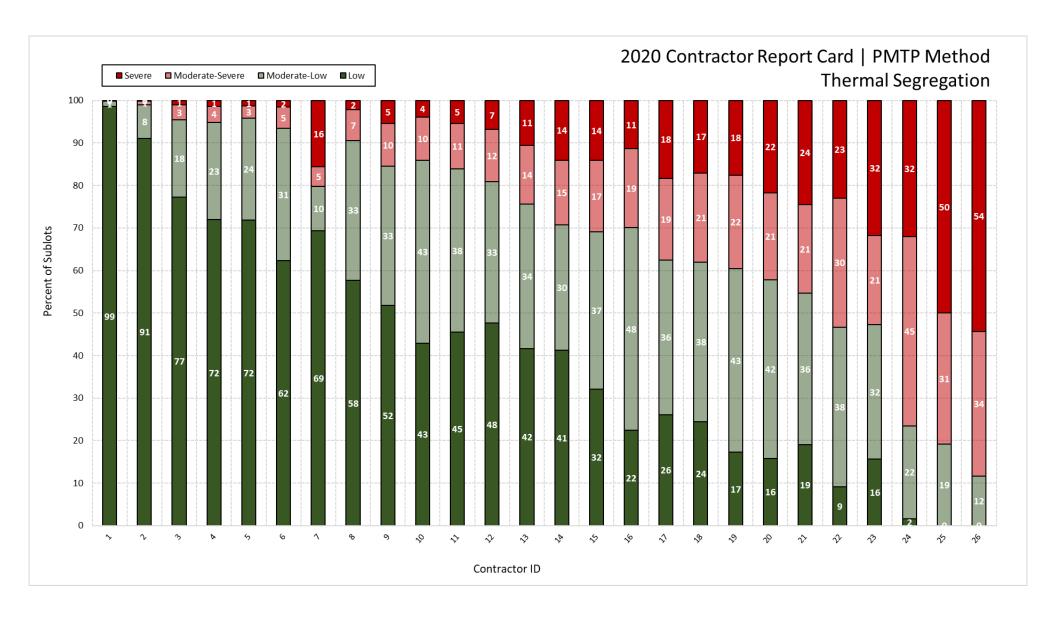




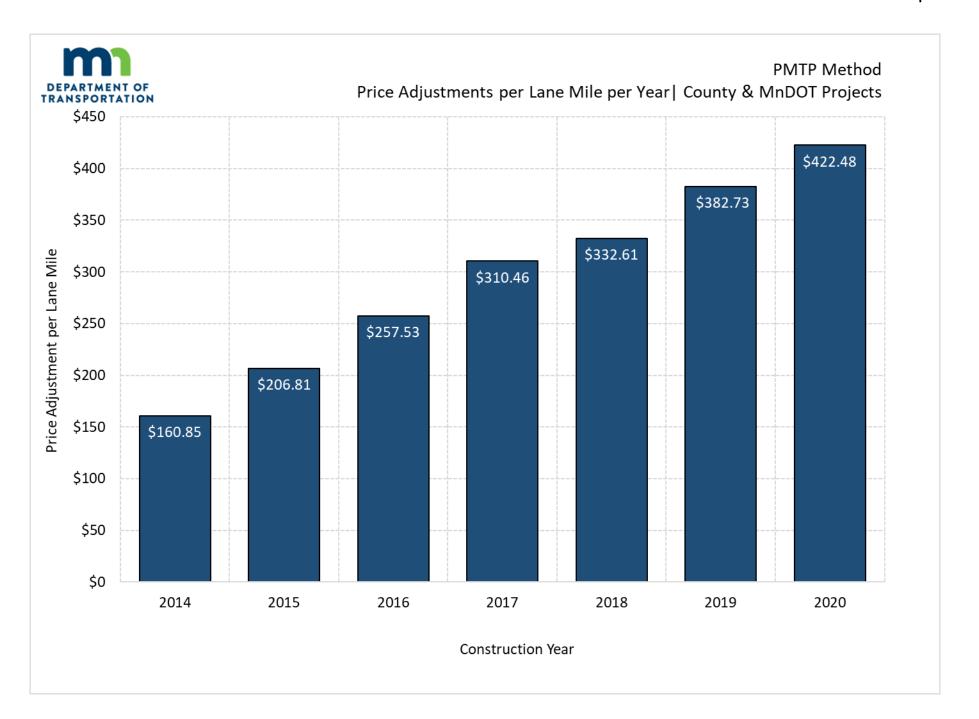




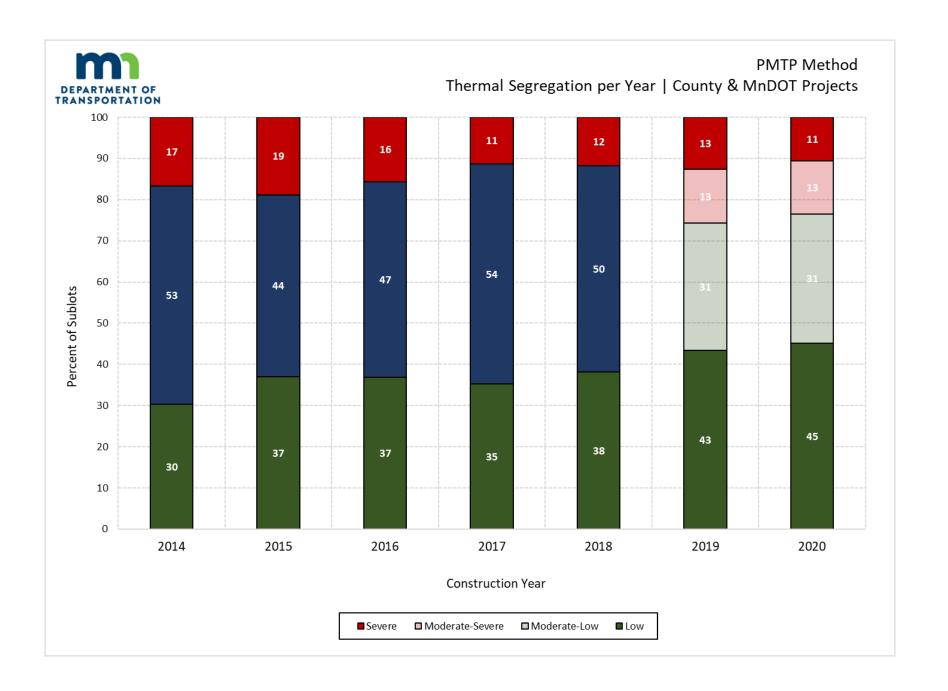




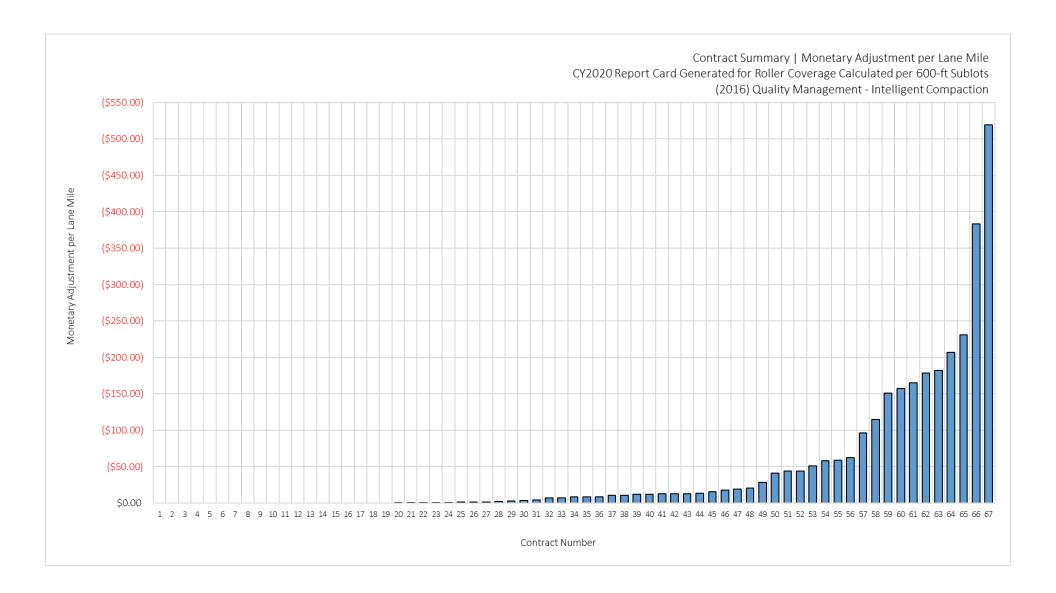




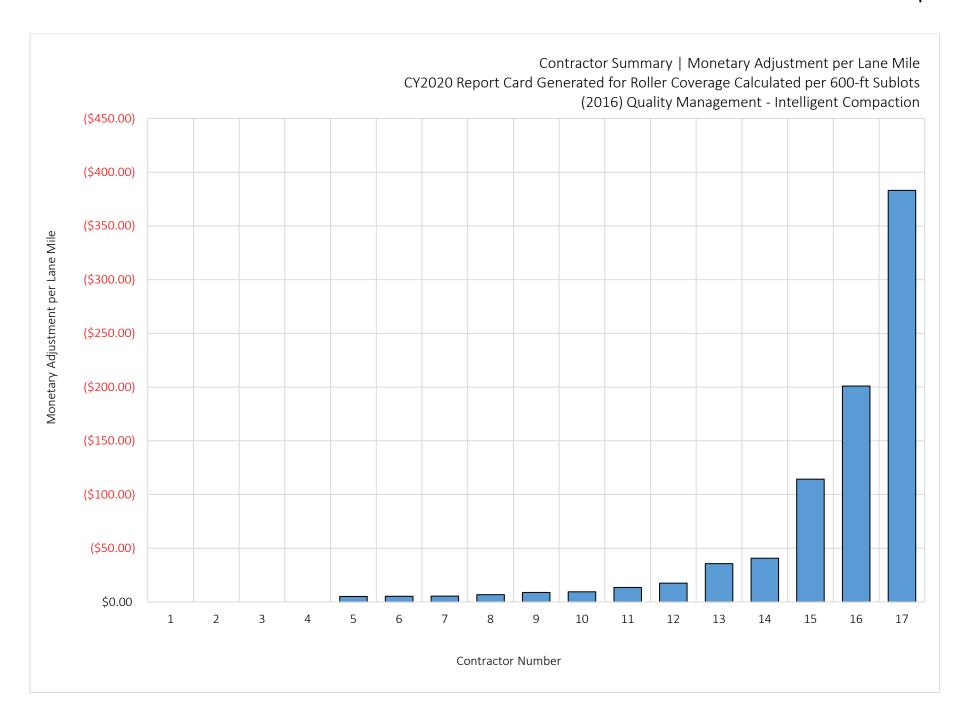




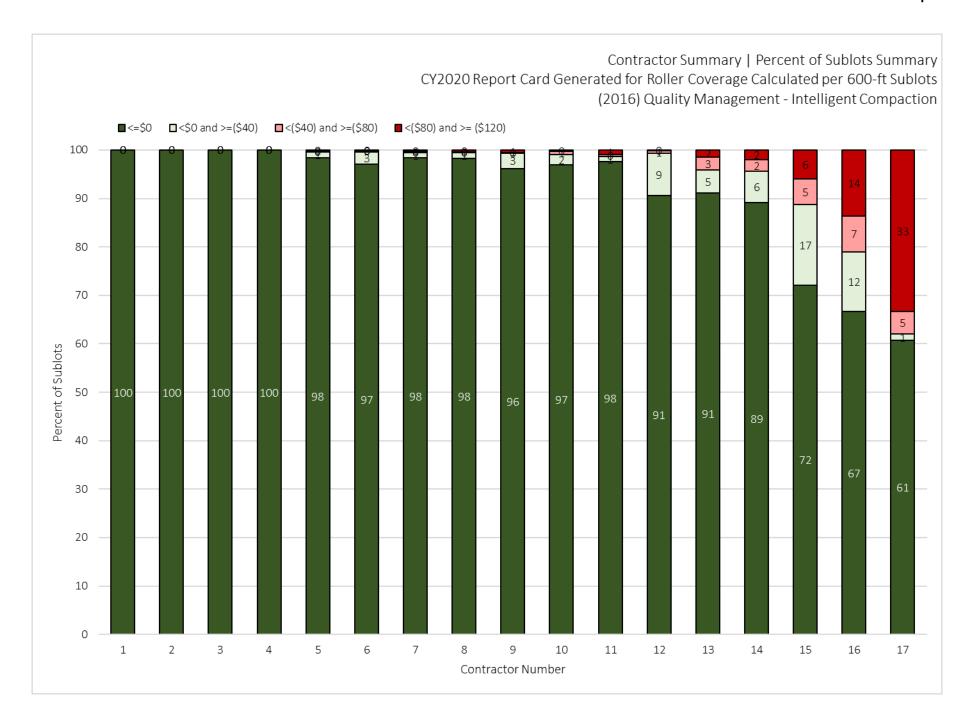




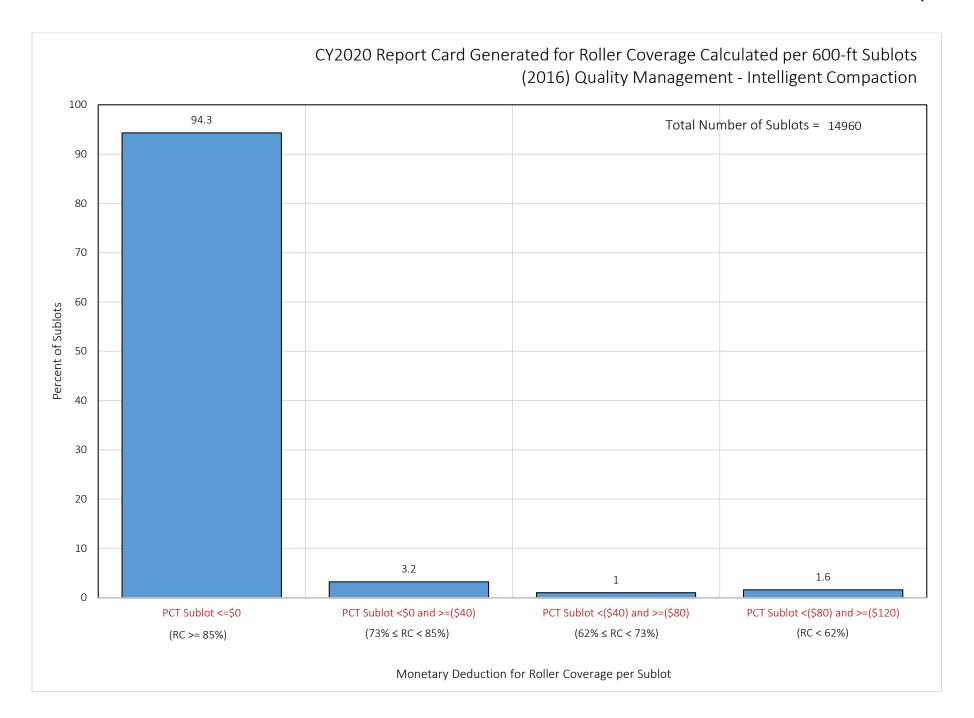




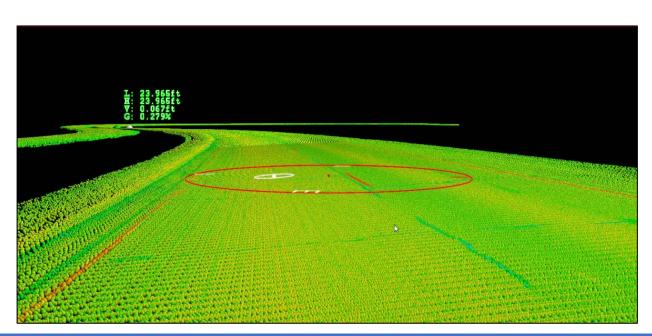


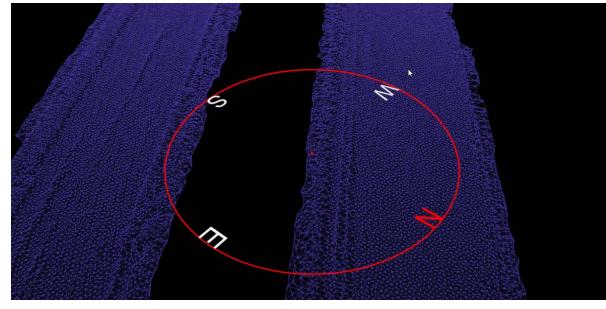












2232 Mill Pavement Surface – Relative AMG Milling Method

# Relative Milling

- Recommended for use when milling an existing asphalt surface for a
  - Mill and Overlay
  - Thinlay
  - Reclamation (e.g., FDR, SFDR, CIR, CCPR)
- Roadmap
  - Piloting Technology on Select Projects
  - Determining model creation workflow, model review checks, ride reviews, etc.
  - Develop Deployment Roadmap

# Variable Depth Milling



This solution uses variable depth milling to achieve a smoothed proposed surface with cross slope corrections.



# Relative Milling

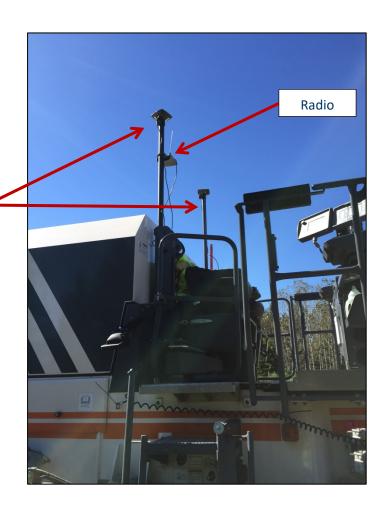
Technology uses the existing surface at a given location to mill to a proposed surface using delta depths vs. absolute elevations.



Technology can use both side gates or side gate- cross slope.

# Components

GNSS
Receivers:
used to track
horizontal
position

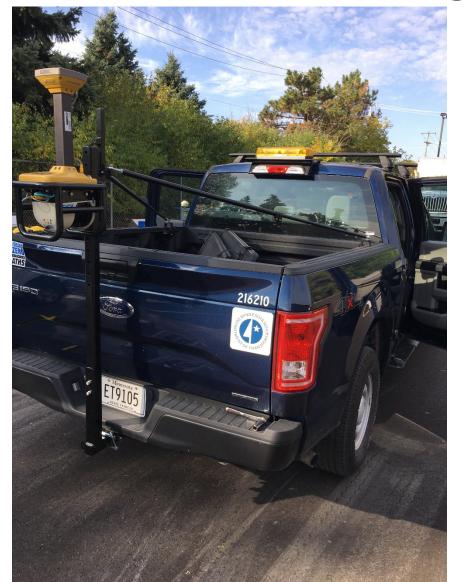




YO-YO Sensor or Sonic Trackers to provide vertical precision

Ski provides 4 ft to average out irregularities.

# Down Facing Lidar Scanner

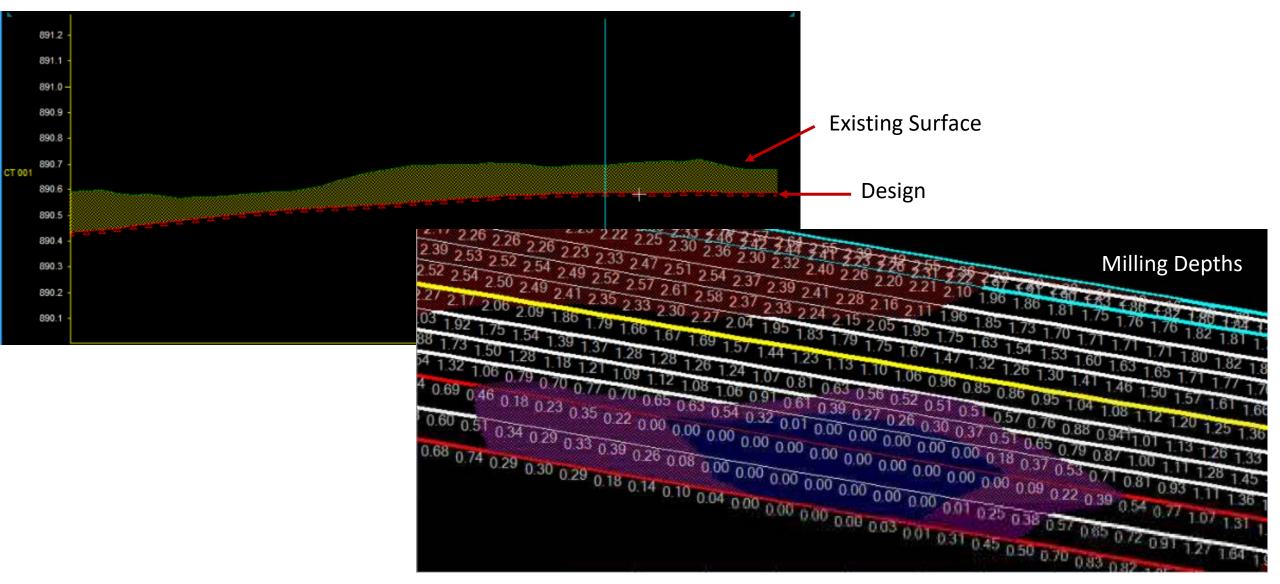


Existing in-place road is scanned to create proposed smoothed milling surface. This surface is also loaded on the milling machine and used as the reference surface during the milling operation.

# Lidar Scan



# Design



# Technology ties into the machine telematics



The operator can view the real time station, proposed cross slope, milling depth and the machine correction factors.

# Onboard Display



# Continuous Quality Control Checks By Contractor



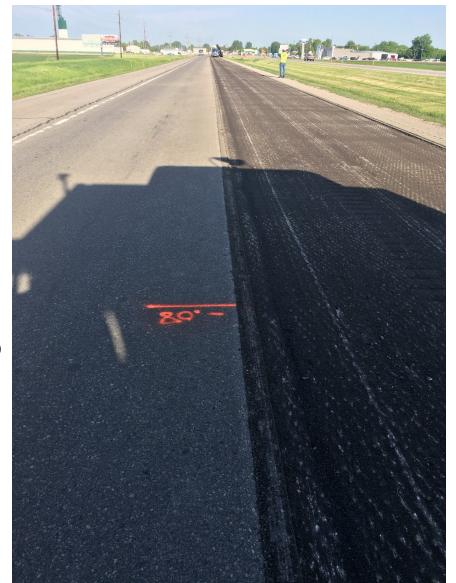
# Quality Assurance By Agency



# Solution is in the Milled Surface



Smoothing and cross slope corrections occur during the milling process resulting in conventional (depth) paving to maintain the proposed surface corrections.



# Questions







### AMG-Milling Method – Robotic Total Stations

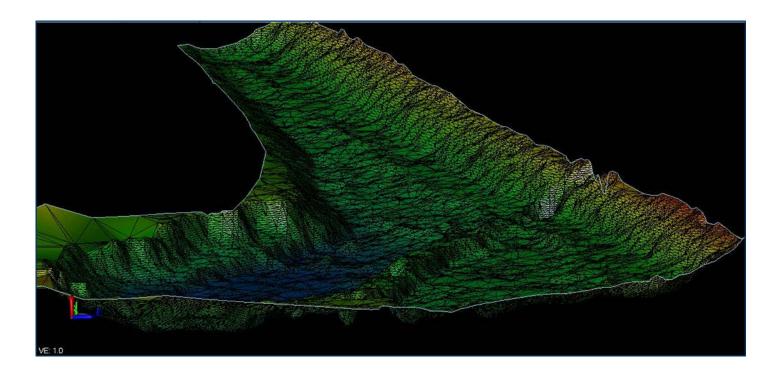
(2232) Milling Pavement Surface – Automated Machine Guidance – Milling Method Using Robotic Total Stations (2011) Construction Surveying – Automated Machine Guidance – Milling Method Using Robotic Total Stations

### AMG-Milling with Robotic Total Stations

Use when placing whitetopping and unbonded concrete overlays on top of a milled asphalt pavement.









#### Automated Machine Guidance – Muck Excavation Method

(2011) Construction Surveying – Automated Machine Guidance – Muck Excavation Method

# Digital Surface Model Method Using the Automated Machine Guidance – Excavation System

#### Description

- Use AMG
  - → continually monitor and record muck excavation operations
  - → create Digital Surface Model for quantification of excavated volumes

#### Recommended

- Muck Excavation Quantities ≥ 30,000 cy, or
- Muck Excavation activities anticipated to be under water (consider size &/or depth of activities)





# Enhancing Highway Foundation Resilience: Intelligent Compaction Applied to Stabilized FDR

Inspector's Workshop OMRR Update February 23, 2021

John Siekmeier P.E. M.ASCE MnDOT Advanced Materials and Technology Maplewood, Minnesota

#### Reminder

Good inspection may add several "hundred"-thousand dollars to the value of the road without adding materially to its cost.

Minnesota Highway Department Construction Manual, 1925

# Opportunity to Eliminate Unsafe Testing



## Opportunity to Implement Performance Tests



# Density Does Not Determine Strength Full Coverage Testing is Important



# Opportunity to Improve Compaction





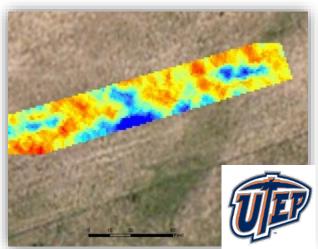
**Drum Movement** 



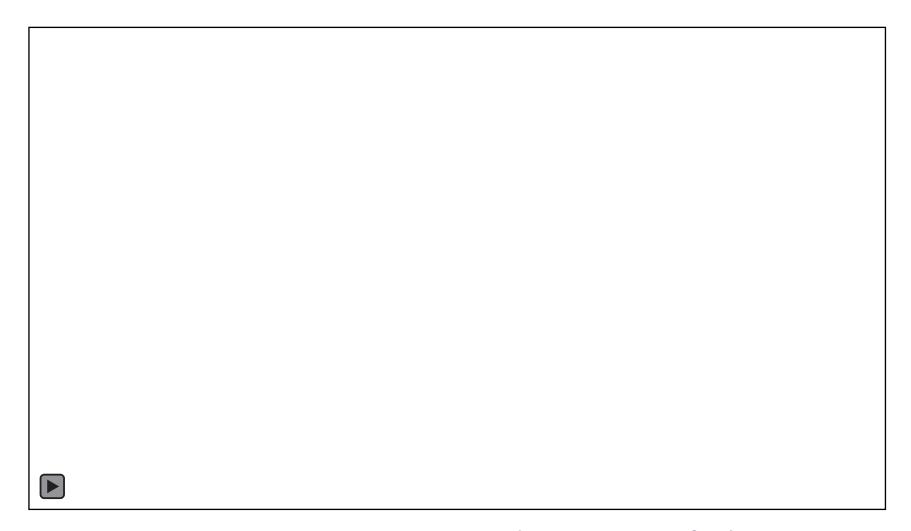
Location



**Compaction Map** 



# Stabilized FDR TH15 2019

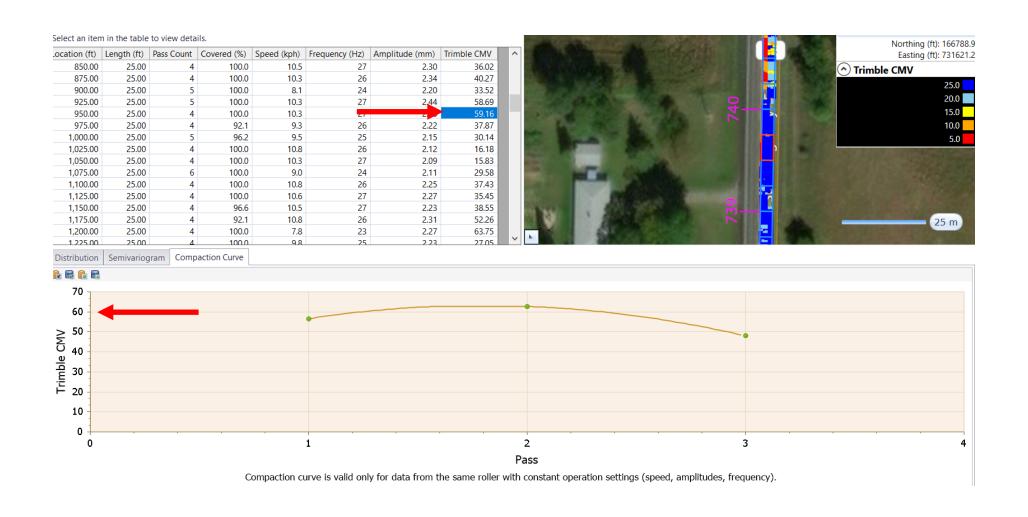


### Roller #1 CP56B

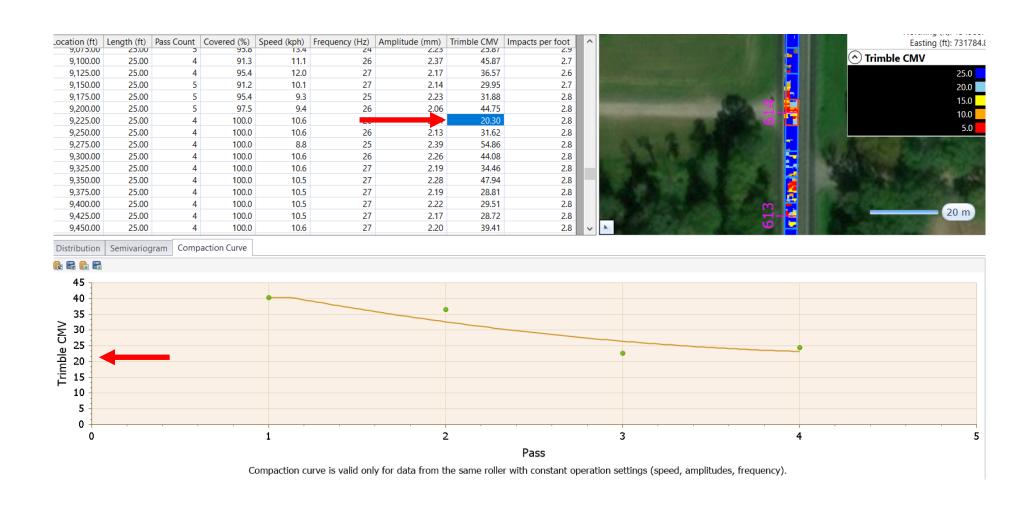


Photo courtesy of Caterpillar

## Compaction Curve (high CMV)



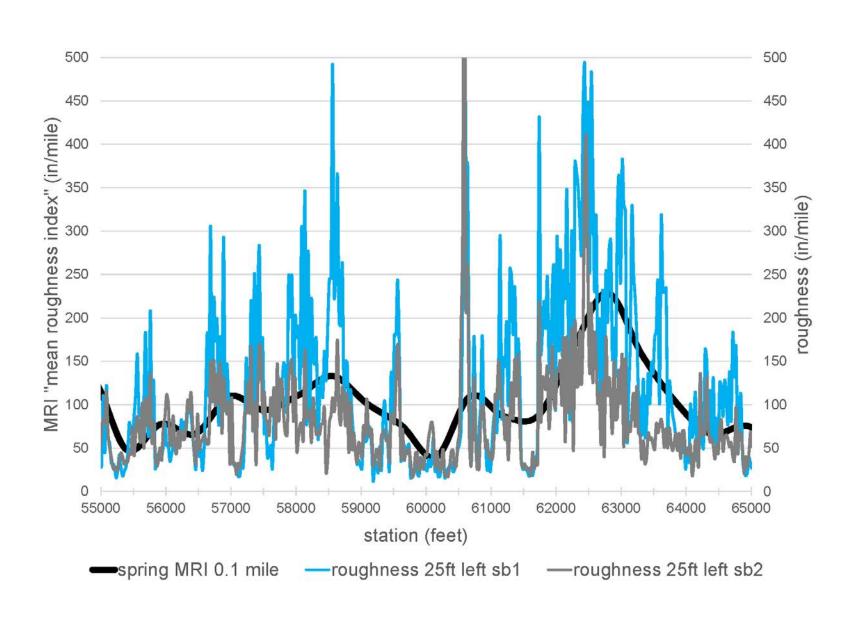
## Compaction Curve (low CMV)



# Vibration and Static Compaction

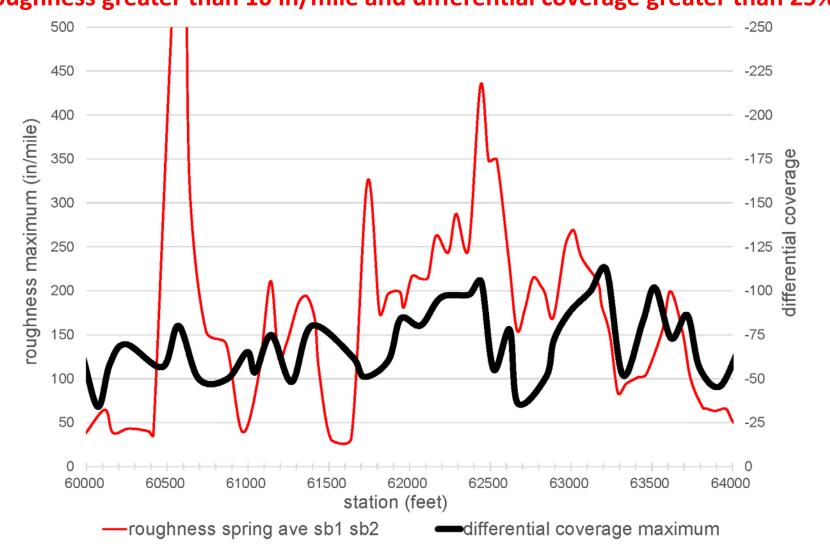


## Spring Roughness



# Roughness and Differential Coverage Maximum

Roughness greater than 10 in/mile and differential coverage greater than 25%.



# Thanks for Listening. Please ask questions

