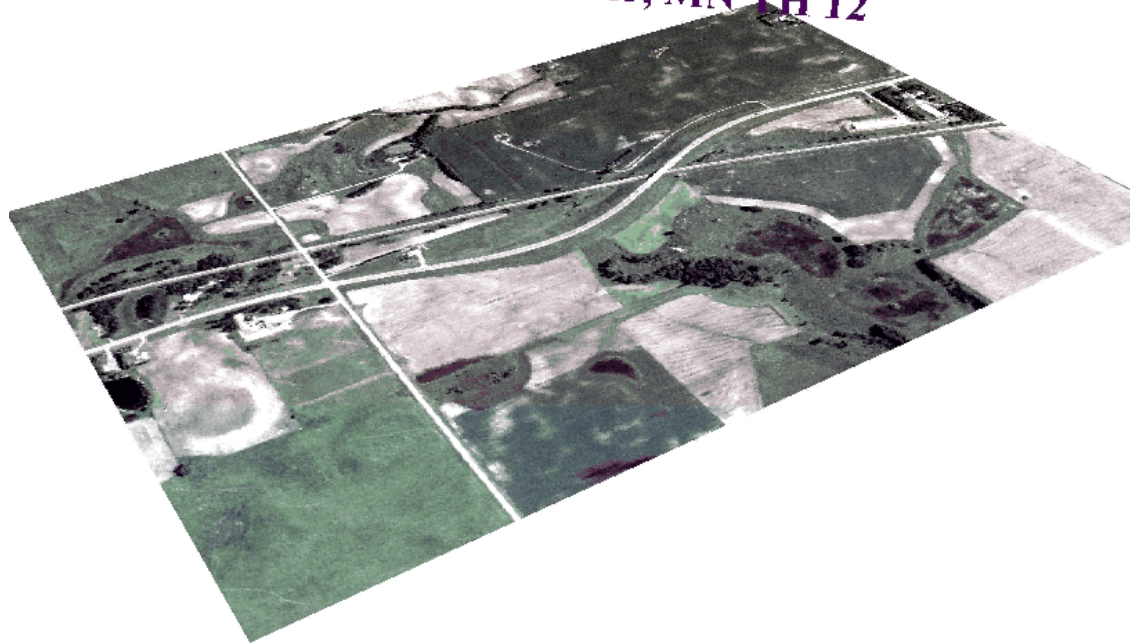
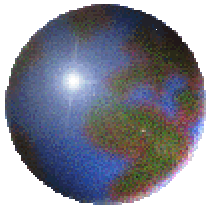


# *3D Visualization of Intelligent Compaction Data*

Atwater, MN TH 12



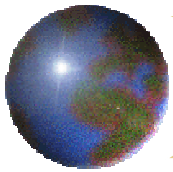
**Ruth Roberson**

**Minnesota Department of Transportation**

Transportation Research Conference

May 24-25, 2006

St Paul, Minnesota

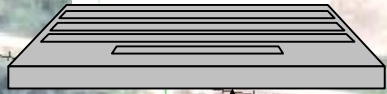
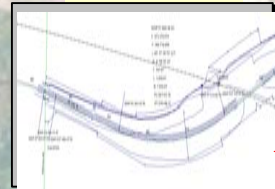


# Design

CAD

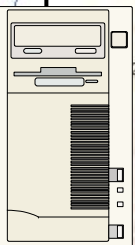
IC

# Construction QC



12INP PI 508+  
 X 473,379.57  
 Y 189,714.40  
 40° 37' 06.72" (L)  
 D 2° 59' 56.33"  
 T 707.07'  
 L 1,354.41'  
 R 1,910.51'  
 PC 501+53.76  
 PT 515+08.17

490  
 495  
 500  
 505  
 510  
 520  
 12INP CS 4  
 12INP ST 493+27.47  
 27.50  
 135th Ave NE



Geodatabase

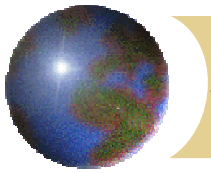
Geospatial Mapping



Construction QA Testing

Pavement Management Archive





# *Current Mn/DOT QC/QA*

## ⊕ Sand cone testing

- ⊕ 100% Proctor

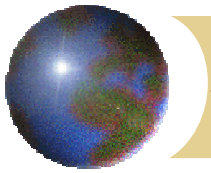
## ⊕ Test rolling

## ⊕ Oven-dry MC

## Problems

- ⊕ Slow results
- ⊕ Inaccurate
- ⊕ Tests / verifies empirical parameter
- ⊕ Unsafe!





# *Mechanistic Testing Equipment*

## ✚ Elastic Modulus

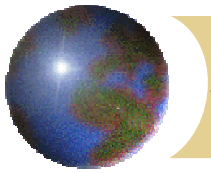
- ✚ Intelligent Compactor (IC)
- ✚ Plate Load Tests (static and quasi-static)
- ✚ Falling Weight Deflectometer (FWD)
- ✚ Light Weight Deflectometer (LWD)
- ✚ Soil Stiffness Gauge (SSG or GeoGauge)

## ✚ Shear Strength

- ✚ Dynamic Cone Penetrometer (DCP)

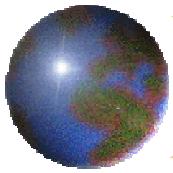




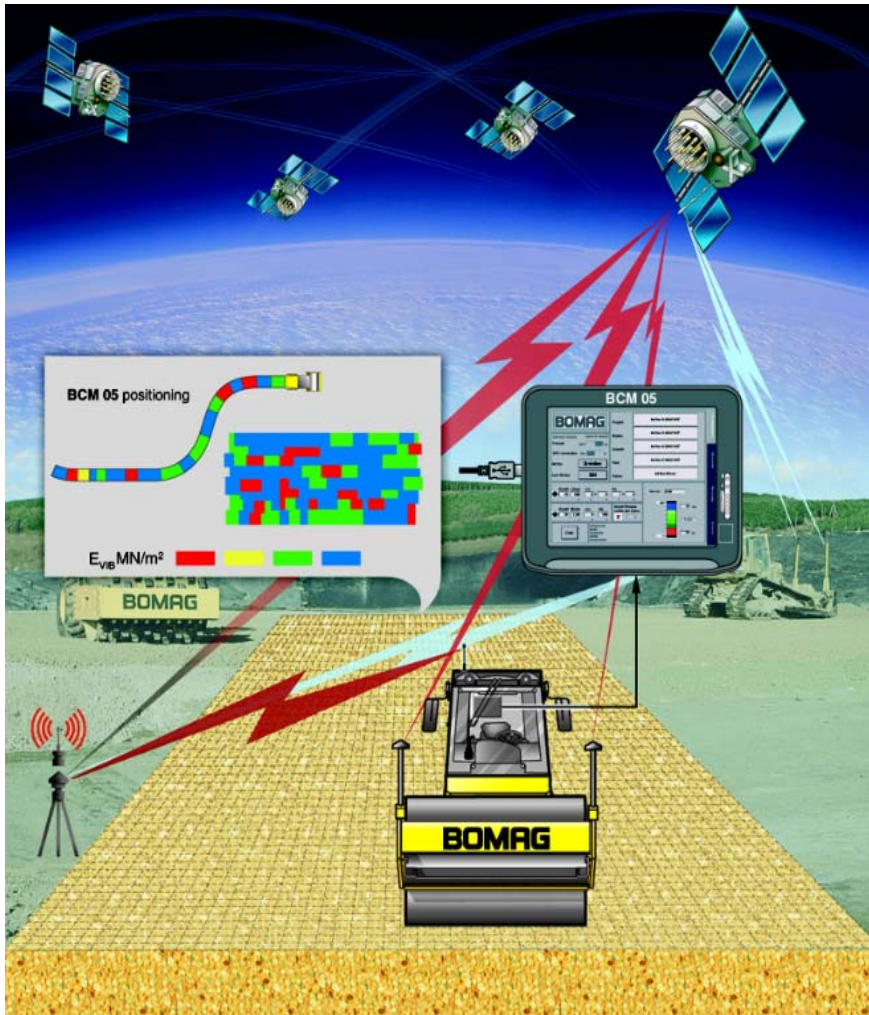


# *Intelligent Compaction in Minnesota*

- The Minnesota Department of Transportation has been investigating intelligent compaction (IC) technology over the past two years.

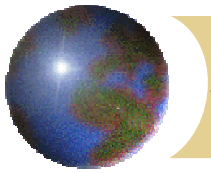


# Intelligent Compaction



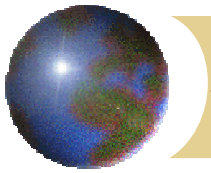
- Continuous calculation of compaction or related parameter
- Automatic adjustment of compactive effort in response to measured material parameter
- Documentation system that provides on-demand color coded mapping of the site





## *Benefits to Mn/DOT*

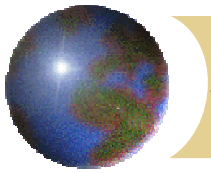
- ⊕ Increased Compaction Uniformity
- ⊕ Complete Documentation of Every Lift
- ⊕ Automation and Better Record Keeping
- ⊕ Improved Inspector Safety
- ⊕ No More Sand Cone Testing



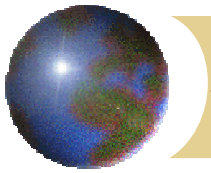
## *2005 Conclusions*

- The compactors were well made, easy to operate, and helped the operator to make better decisions.
- Intelligent compactors can measure the stiffness of the ground and adjust their compactive force as needed.
- Surface covering documentation can be produced.
- Data transfer was functional, but must be improved.





# *How We Handle the Data?*



## *IC Roller Similarities*

- Single drum vibratory rollers
- GPS System
- Stiffness / Modulus estimated
- Mapping System

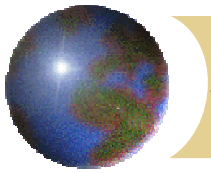


## *IC Roller Differences*

- Geographic Positioning System (GPS)
- Data File Format and Information
  - Coordinate and Projection System
  - Timestamp
  - Manufacturer Specific Output (Passes)







# *Field QA Inspection Implementation*

- ⊕ Technologically “Easy” to Use
  - ⊕ Handling the data
- ⊕ Field Rugged
  - ⊕ Palm pilot
  - ⊕ laptop
- ⊕ Scientifically Rigorous
  - ⊕ Preprocessing geostatistics





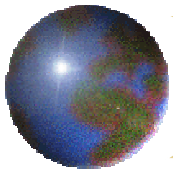
# *Data Needs for Identifying Quality Assurance Test Locations.*

- Mapping system
  - ❑ Import compactor data as it becomes available.
  - ❑ Superimpose compactor data on construction plans.
- Final Compaction Layer (Proof Layer)
  - ❑ Coordinates (x,y)
  - ❑ Stiffness / Modulus estimated
  - ❑ Timestamp
- Inspection Points
  - ❑ Engineering judgement
  - ❑ Use new material specifications and geostatistical methods to determine locations for quality assurance testing.

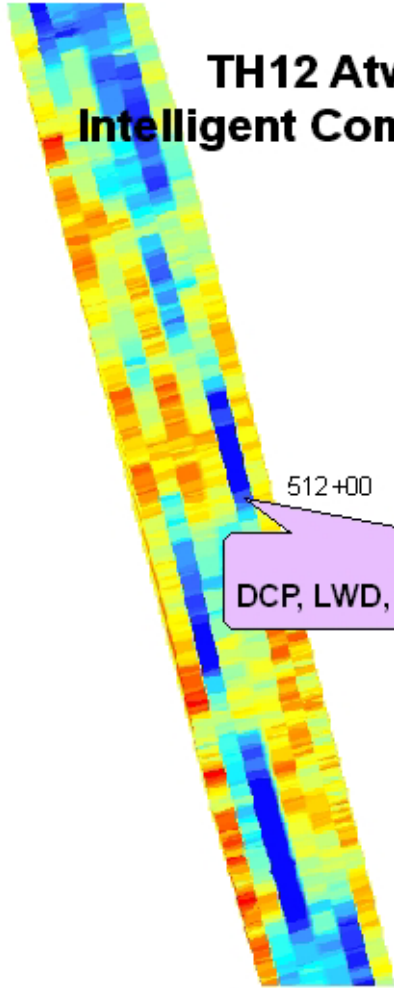








# TH12 Atwater, Mn Intelligent Compaction Demo

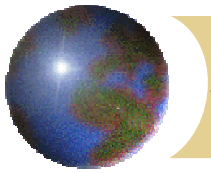


512+00

Location 1  
DCP, LWD, Geogage Measurements



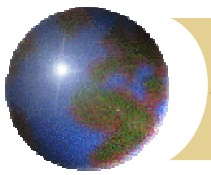




# *Implementing Simplified QA Method*

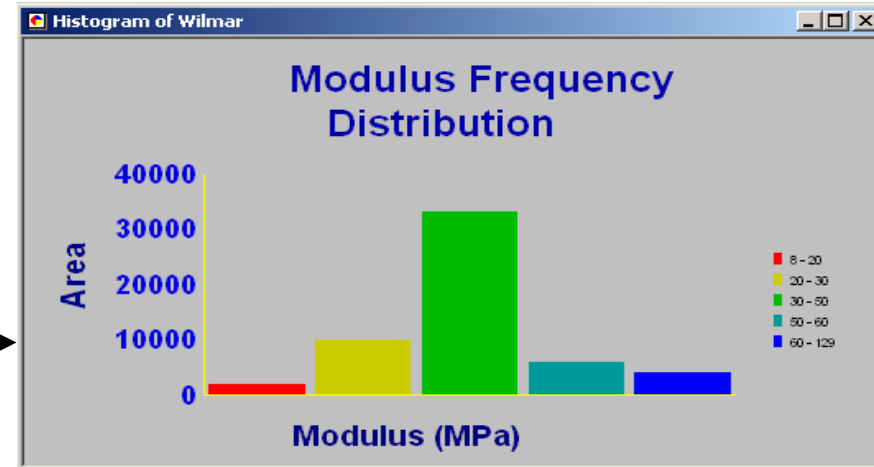
## ✚ **Development Framework**

- ✚ ASCII text file (as defined by MnDOT IC specification)
- ✚ Histogram
- ✚ Linear Model for Surface Plot
- ✚ Engineering Judgment

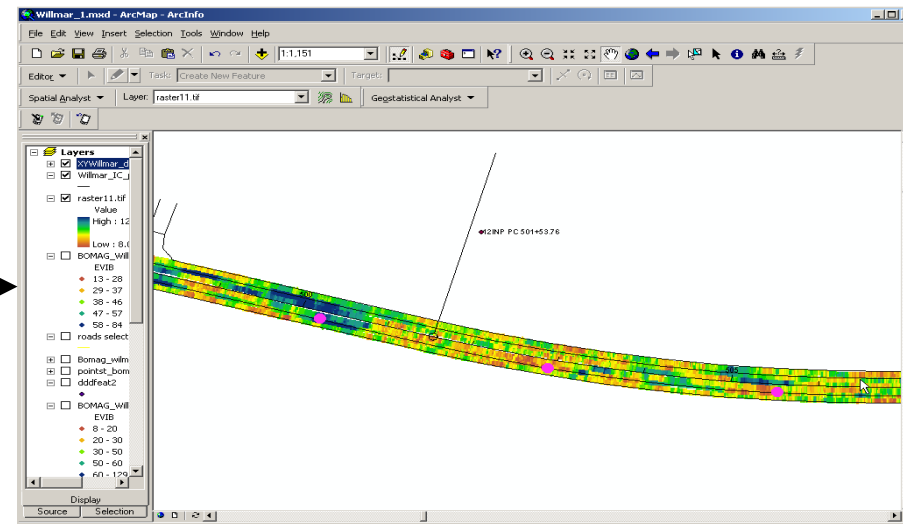
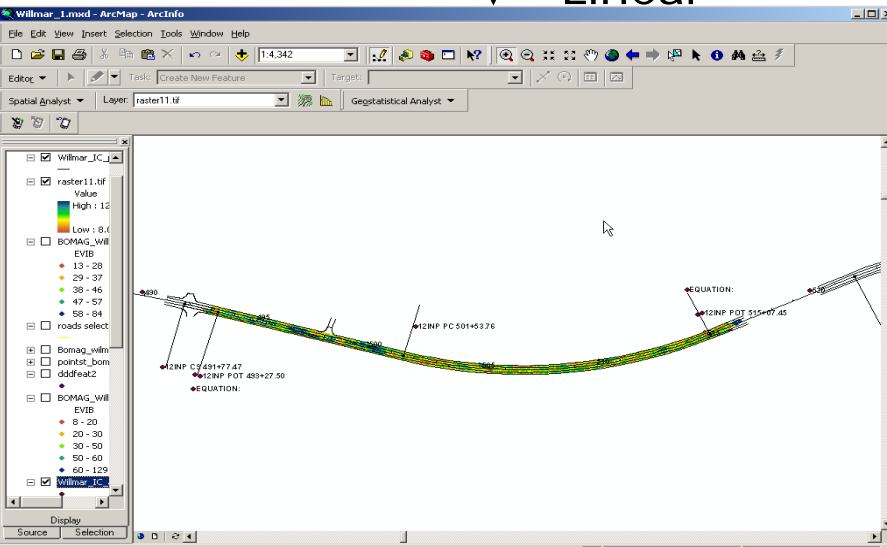


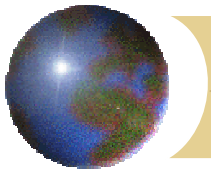
# Implementing Simplified QA Method

PositionX	PositionY	PositionZ	EVIB
57944.01	143812.1	380.062	36
57944.11	143812.1	380.062	36
57943.91	143812.2	380.073	58
57944.01	143812.2	380.073	58
57944.11	143812.2	380.062	36
57944.21	143812.2	380.062	36
57944.31	143812.2	380.062	36
57943.91	143812.3	380.08	58
57944.01	143812.3	380.073	58
57944.11	143812.3	380.073	58
57944.21	143812.3	380.073	58
57944.31	143812.3	380.062	36
57944.41	143812.3	380.062	36
57944.51	143812.3	380.062	36
57943.81	143812.4	380.08	58
57943.91	143812.4	380.08	58
57944.01	143812.4	380.08	58



Linear



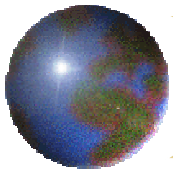


# *Implementing Geostatistically- Based QA Testing*

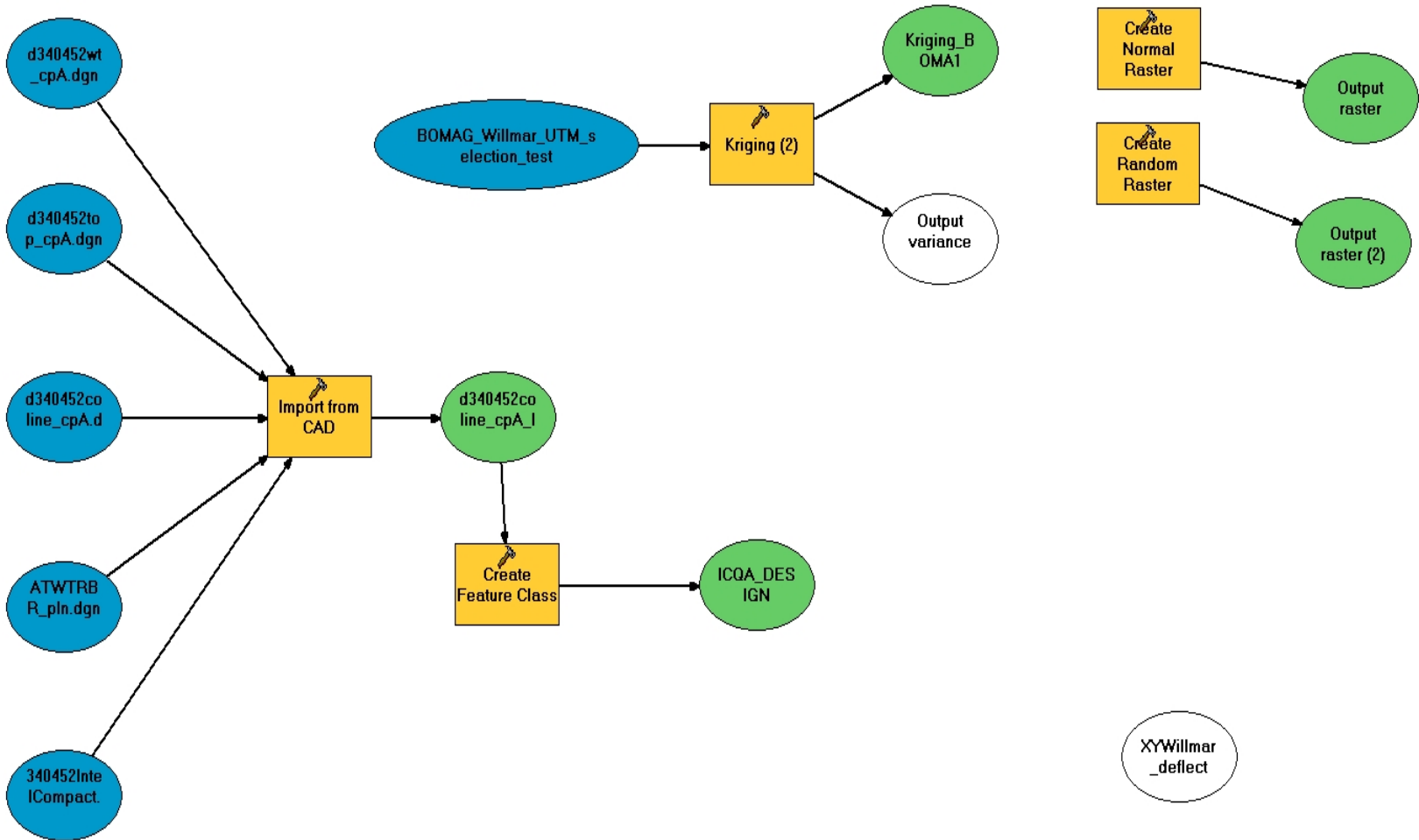
## ✚ **Development Framework**

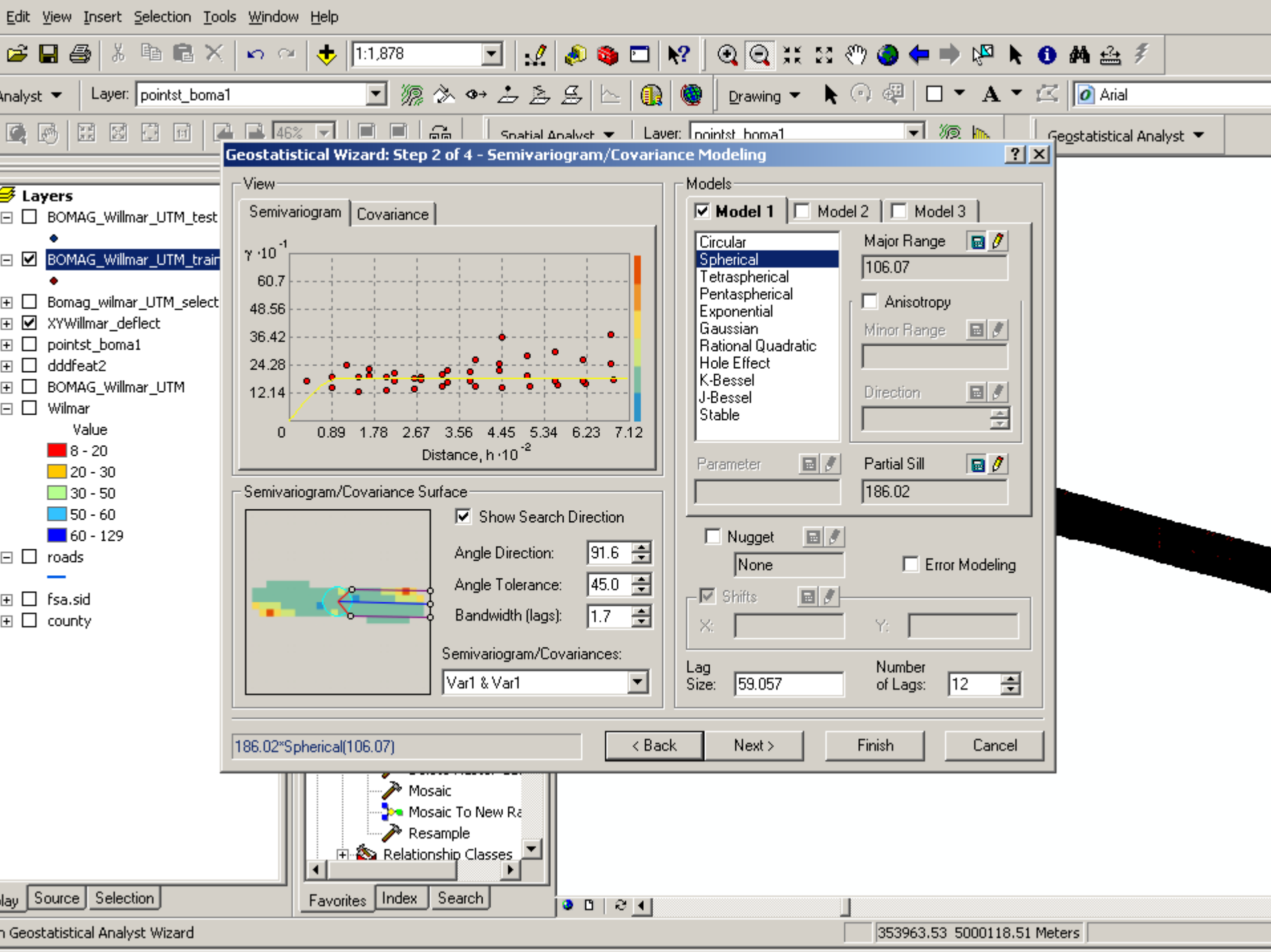
- ✚ ASCII text file (as defined by MnDOT IC specification)
- ✚ Generate Variogram
  - ▣ Based on greatest lag distance with least amount of variability
- ✚ Final output is Map containing CAD drawing, aerial photo, compactor data, and QA sampling coordinates



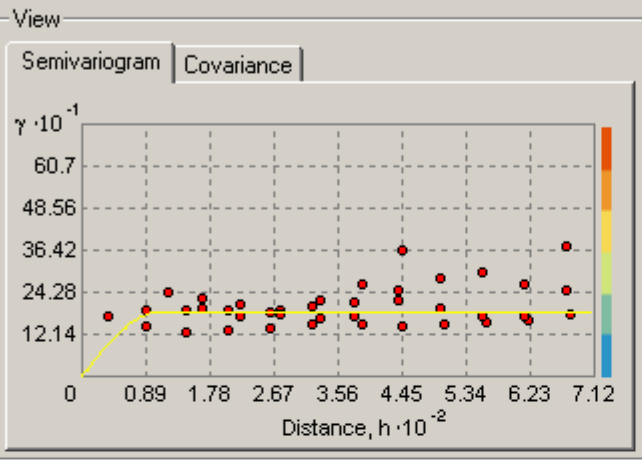


# Data Model





Geostatistical Wizard: Step 2 of 4 - Semivariogram/Covariance Modeling



Models

Model 1  Model 2  Model 3

Circular  
**Spherical**  
Tetraspherical  
Pentaspherical  
Exponential  
Gaussian  
Rational Quadratic  
Hole Effect  
K-Bessel  
J-Bessel  
Stable

Major Range: 106.07

Anisotropy

Minor Range: [ ]

Direction: [ ]

Parameter: [ ] Partial Sill: 186.02

Nugget: None  Error Modeling

Shifts

X: [ ] Y: [ ]

Lag Size: 59.057 Number of Lags: 12

Semivariogram/Covariance Surface

Show Search Direction

Angle Direction: 91.6

Angle Tolerance: 45.0

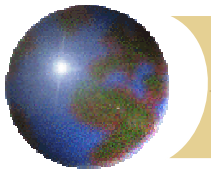
Bandwidth (lags): 1.7

Semivariogram/Covariances: Var1 & Var1

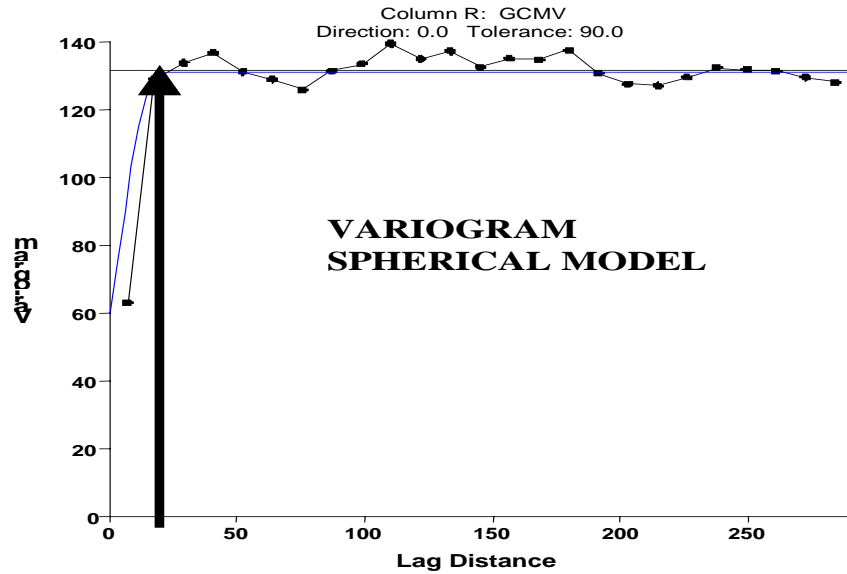
186.02\*Spherical(106.07) < Back Next > Finish Cancel

Mosaic  
Mosaic To New Raster  
Resample  
Relationship Classes

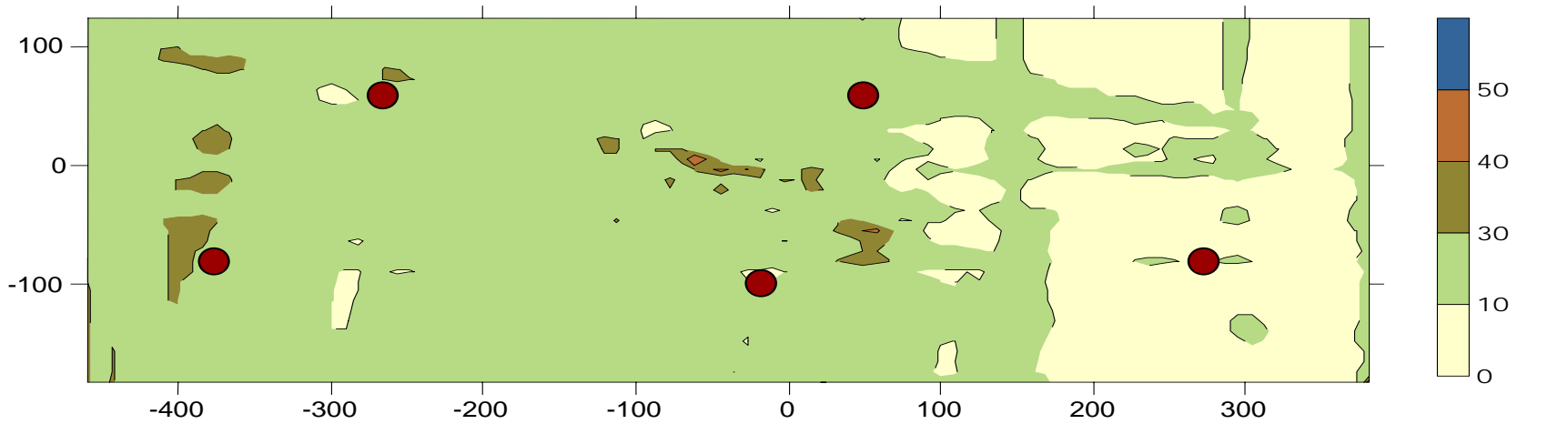
Favorites Index Search



# Data Model

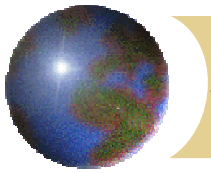


● QA TESTING LOCATIONS



**CONTOURED GRID**



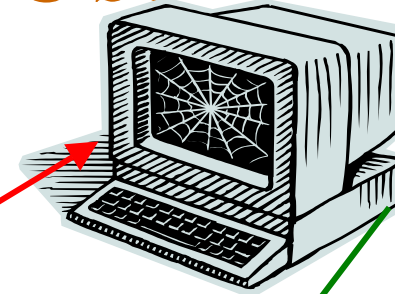
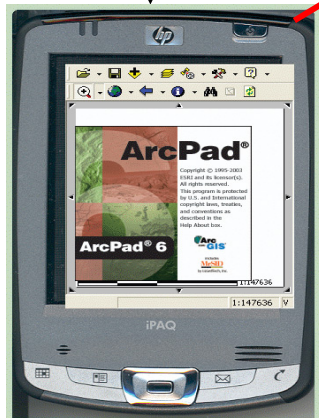


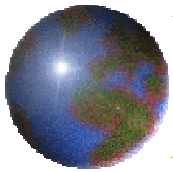
# *Evaluating Devices for Field Implementation*



# Palm Device for Field Use

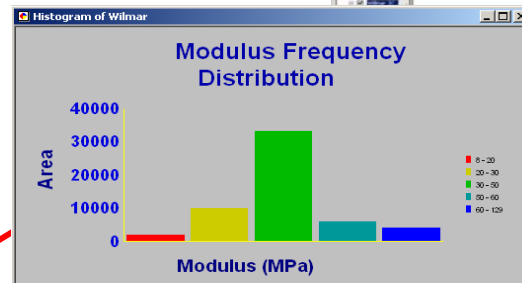
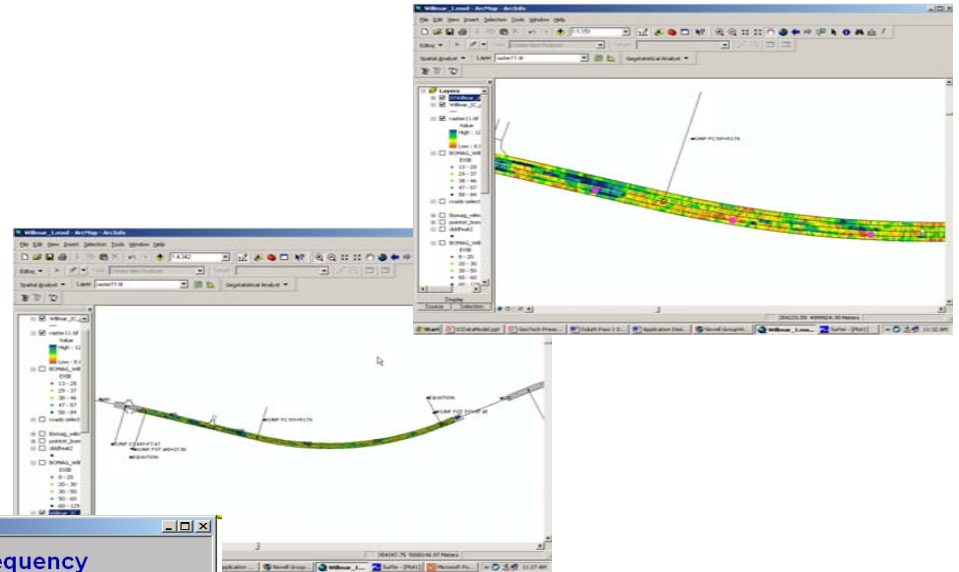
PositionX	PositionY	PositionZ	EVIB
57944.01	143812.1	380.062	36
57944.11	143812.1	380.062	36
57943.91	143812.2	380.073	58
57944.01	143812.2	380.073	58
57944.11	143812.2	380.062	36
57944.21	143812.2	380.062	36
57944.31	143812.2	380.062	36
57943.91	143812.3	380.08	58
57944.01	143812.3	380.073	58
57944.11	143812.3	380.073	58
57944.21	143812.3	380.073	58
57944.31	143812.3	380.062	36
57944.41	143812.3	380.062	36
57944.51	143812.3	380.062	36
57943.81	143812.4	380.08	58
57943.91	143812.4	380.08	58
57944.01	143812.4	380.08	58

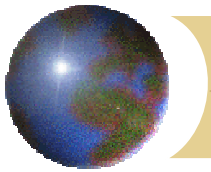




# Laptop for Field Use

PositionX	PositionY	PositionZ	EVIB
57944.01	143812.1	380.062	36
57944.11	143812.1	380.062	36
57943.91	143812.2	380.073	58
57944.01	143812.2	380.073	58
57944.11	143812.2	380.062	36
57944.21	143812.2	380.062	36
57944.31	143812.2	380.062	36
57943.91	143812.3	380.08	58
57944.01	143812.3	380.073	58
57944.11	143812.3	380.073	58
57944.21	143812.3	380.073	58
57944.31	143812.3	380.062	36
57944.41	143812.3	380.062	36
57944.51	143812.3	380.062	36
57943.81	143812.4	380.08	58
57943.91	143812.4	380.08	58
57944.01	143812.4	380.08	58

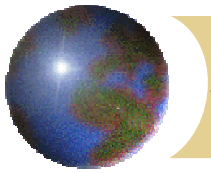




# *Conclusions: Data Format*

- ❖ Need standardized data format
  - ❑ Roller Parameters
    - Frequency, Amplitude, Acceleration of Drum
  - ❑ Position data that includes x,y, and z-coordinates for both sides of the drum in UTM NAD 1983 zone 15N
  - ❑ Time stamp for each data point accurate to frequency of the drum





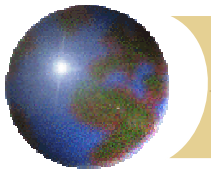
# *Conclusions: Data Processing*

- Simplified QA Method
  - Fast and Easy
  - Data intensive
  - Engineering Judgment
- Geostatistically-based Method
  - Relatively fast and easy
  - Preprocessing
  - Scientifically rigorous
  - Objective



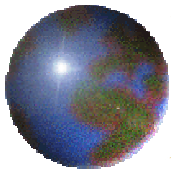
## *Conclusions: Field Devices*

- HP Palm: slow processor, ArcPad cannot preprocess data, has wireless and GPS capabilities.
  - Neither Simplified or Geostatistics Method
  - Displays already processed data / data collection
  
- Laptop (TOUGHBOOK) can Map and process data, ArcView, wireless capabilities.
  - Both Simplified or Geostatistics Method
  - Displays already processed data / data collection



# *IC Resources*

- ⊕ <http://www.dot.state.mn.us/const/tools/innovativecontract.html>
- ⊕ [http://mnroad.dot.state.mn.us/research/ictgi/ictgi\\_welcome.asp](http://mnroad.dot.state.mn.us/research/ictgi/ictgi_welcome.asp)
- ⊕ Mn/DOT Participation with Other DOTs
  - ⊞ FHWA-led Intelligent Compaction Pooled Fund
  - ⊞ NCHRP 21-09 Intelligent Compaction Specifications
    - Open House/Demonstration at MnROAD



# ICTGI Team 2005

## Abstracts/Papers/Reports:



- Ruth Roberson
- Bruce Chadbourn
- John Siekmeier

- Cassie O'Neal
- Felipe Camargo
- Peter Davich
- Agueda Guerra
- Brett Larsen

1. **Validation of DCP and LWD Moisture Specification for Granular Materials**, LRRB INV829, September, 2005. *Peter Davich, Brett Larsen, Felipe Camargo, John Siekmeier, Ruth Roberson*
2. **Shear Strength of Soils as Influenced by Matric Potential**, 2005 ASA-CSSA-SSSA International Annual Meetings Salt Lake City, UT - November, 2005. *Andry Ranaivoson, John Siekmeier, Ruth Roberson, Satish Gupta*
3. **Intelligent Compaction – A Case History**, 54<sup>th</sup> Annual GeoTechnical Engineering Conference, February, 2006 . *Felipe Camargo, Brett Larsen, Peter Davich, Ruth Roberson, John Siekmeier*
4. **Moisture Retention Characteristics of Aggregate And Granular Materials**, Unsaturated Soils Conference 2006, Phoenix, AZ –April 2006 *Amanjot Singh, Ruth Roberson, Andry Ranaivoson, John Siekmeier, and Satish Gupta*

