

The background of the slide is a photograph of a concrete bridge structure. The bridge has multiple large, rectangular concrete pillars supporting a wide, flat deck. The perspective is from below the bridge, looking up at the underside of the deck and the supporting pillars. The lighting is bright, suggesting a sunny day. The text is overlaid on this image.

Non-Destructive Testing in Civil Engineering

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Bridge Testing

In Germany according to DIN 1076

- Regular inspection 3 y
- In depth inspection 3 y after Regular inspection
- Special inspection (e.g. after accident or climatic hazard)



NDT:

- Special Inspection
- Procedure





UngROUTED Tendon Ducts

**Not uncommon
problem in
bridges built
1960-80**



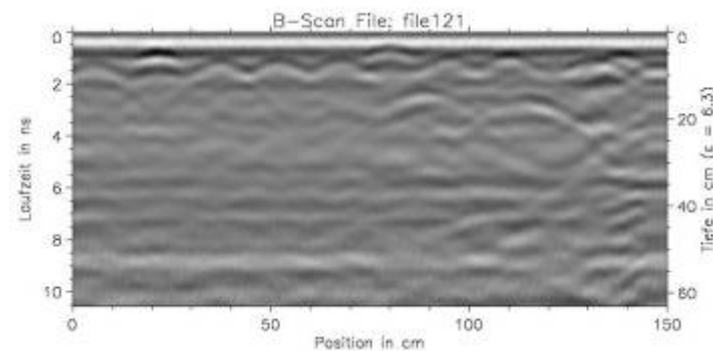
- Measuring the thickness and geometry
- Tendon ducts
 - Position
 - Concrete cover
 - Grouting
 - Honeycombs (around them)
 - Corrosion of strands
 - Cracks and fissures in strands
- Concrete
 - Reinforcement (position, cover, diameter)
 - Localisation of honeycombs
 - Delaminations
 - Cracks (position, depth)
- Quality assurance of construction
-

The Methods

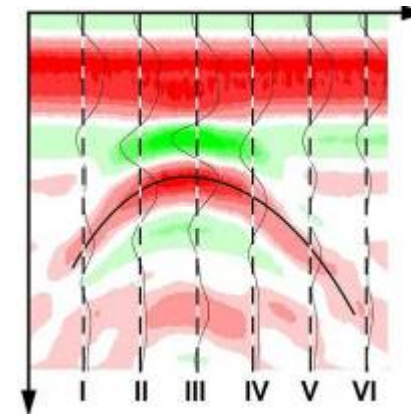
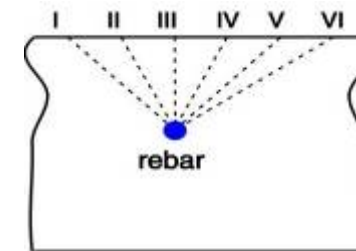
Impulse Echo Principle

(1) Electro-Magnetic Method Radar

- Reflections at interfaces of materials with different dielectric properties
- Antenna of 900 MHz and 1.5 GHz



Position of antennas



Radar gram with hyperbola

(2) Acoustic Methods Ultrasonic Echo/ Impact-Echo

- Reflections at interfaces of materials with different acoustical properties

Ultrasonic Measurement Device



- **Shear waves**
 - center frequency of 50 kHz
- **Measurement head**
 - 24 point-contact transducers
 - without coupling agent

Impact-Echo Measurement Device



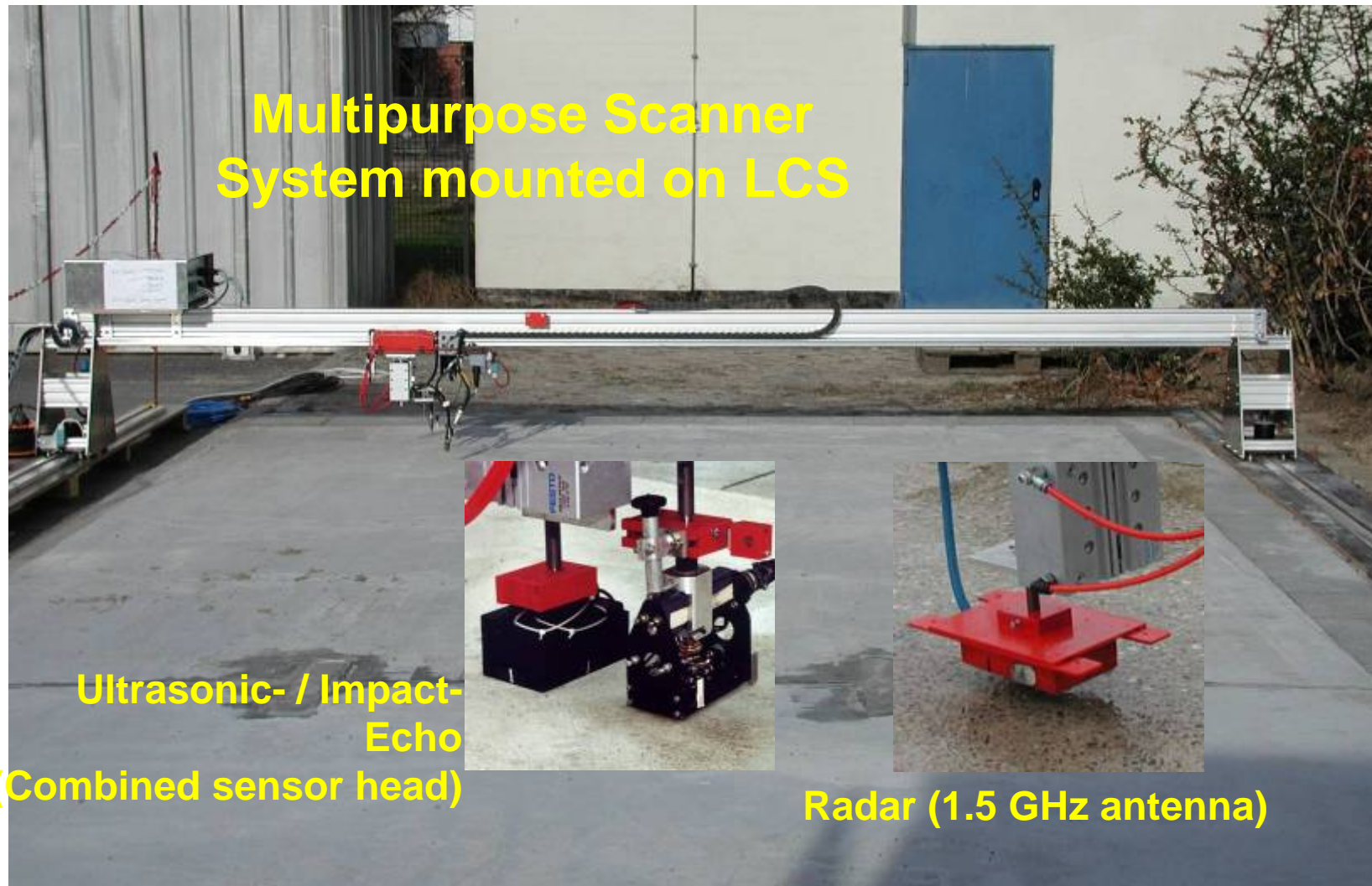
- **Frequency range**
 - from 1Hz to 40 kHz
- **Frequency spectrum analysis**
 - multiple reflections (recorded in the time domain)

Automation and Scanning



Scanning Area Speed:

- Ultrasonic Echo/Impact Echo
1m²/h, 0.02 m point grid
- Radar
15m²/h, 0.05 m line grid





Scanner Systems

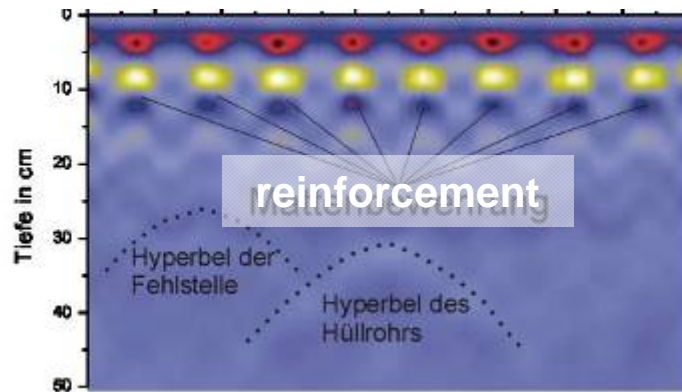


- ▶ Small lightweight scanner with vacuum attachment
- ▶ Two ultrasound sensors (dry coupled) to reduce measurement time

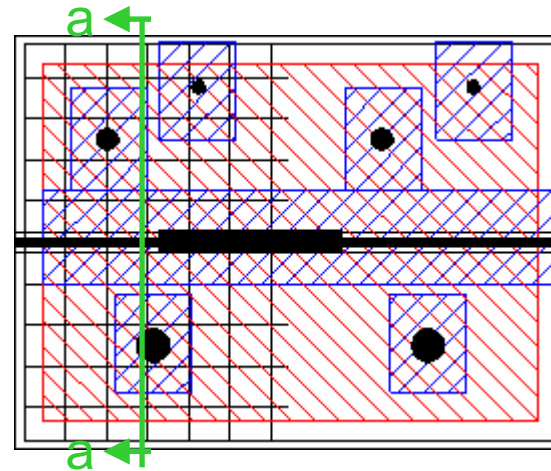


Data Fusion and Visualization

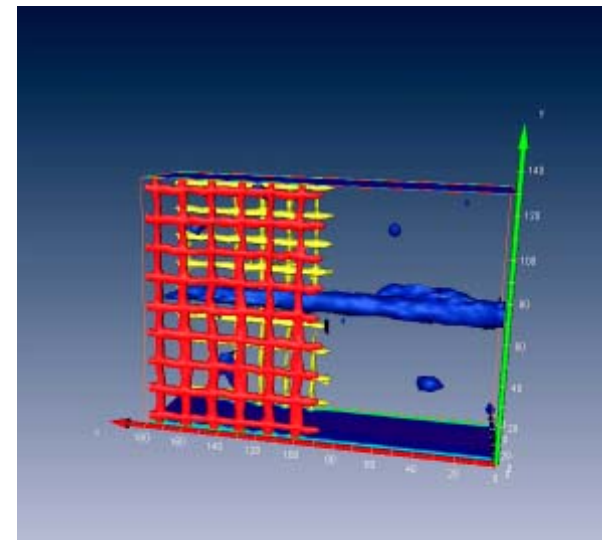
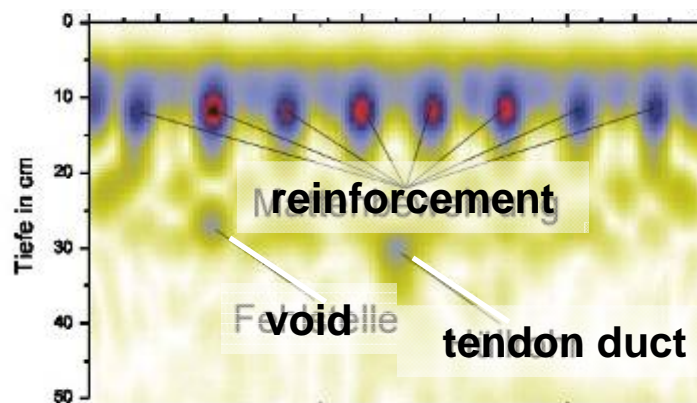
Section a-a without reconstruction calculation



Reinforced concrete slab

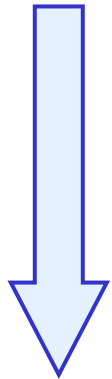


Section a-a with reconstruction calculation



3-D imaging of the results

2-dimensional measurement on the surface of structures



- B-Scan
plots perpendicular to the measurement surface (x-y plane)
- C-Scan
plots parallel to the measurement surface (x-y plane)

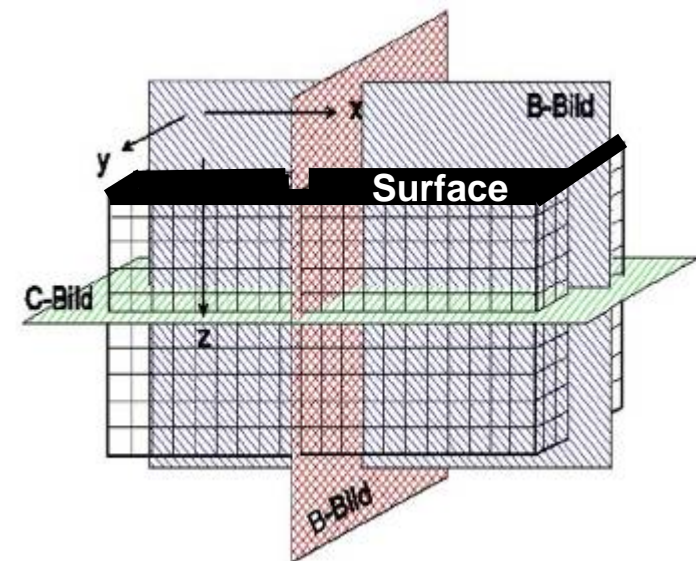
Projections and Animations of consecutive scans

3D-Reconstruction

Focusing of reflected signals using SAFT
(Synthetic Aperture Focusing Technique)

Data Fusion

Superposition of data



Validation

Large Concrete Slab (LCS) at BAM



Facility for various tests and measurements for the improvement of NDT-CE methods

Reference specimen for comparison of different methods (=>validation)

1. Section - Tendon ducts



11 Tendon ducts with strands
(length 4 m, diameter 40 ... 100 mm)
Grouting defects, Grouting by DSI



2. Section - Voids and auxiliary devices

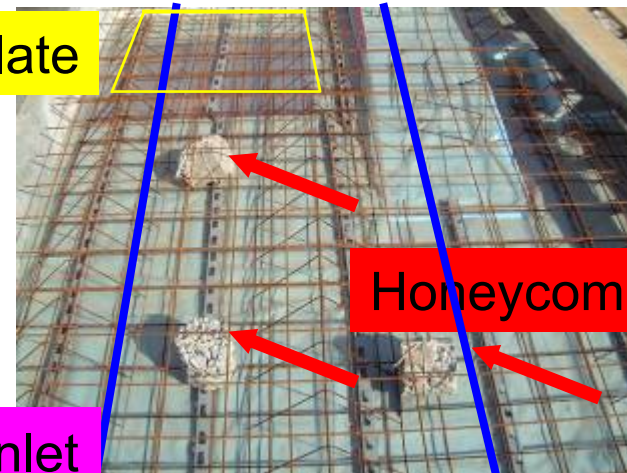
Voids:

- Compaction faults (gravel pockets)



Steel-plate

Thermoelements

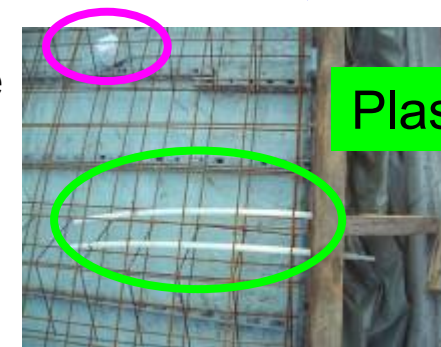


Honeycombs

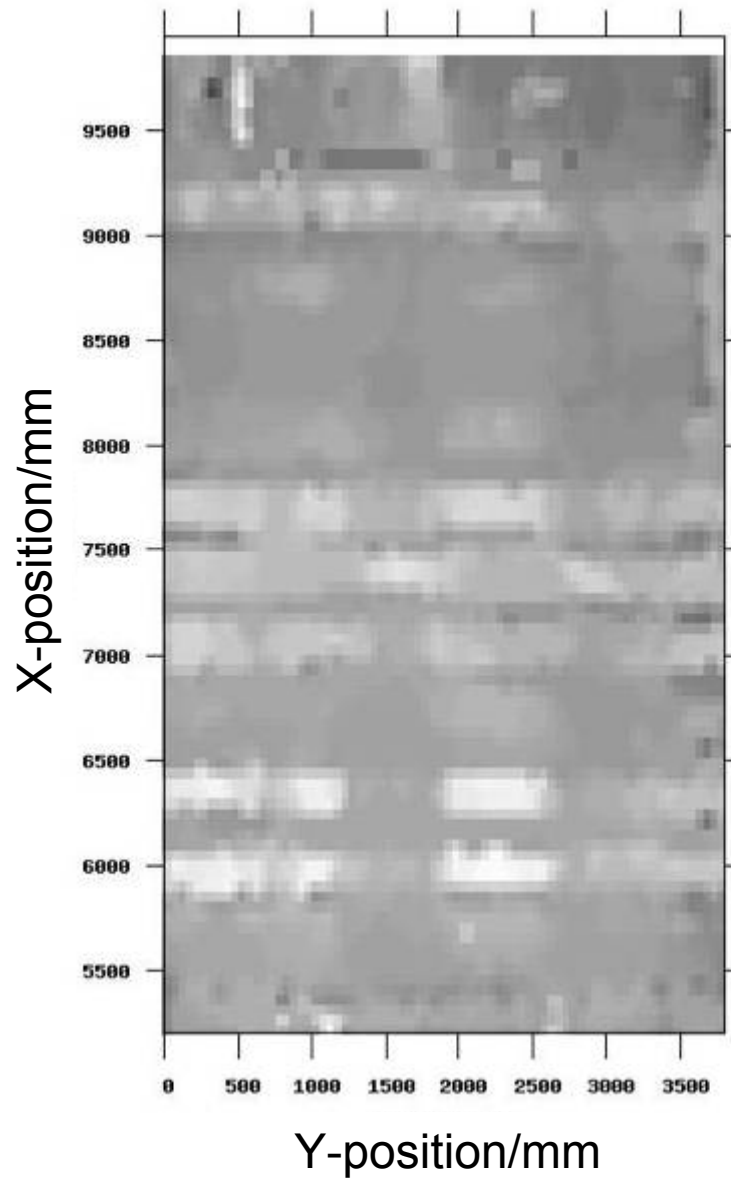
Water inlet

Auxiliary elements:

- Inlet for water and salt-solution through a tube from the bottom side into high porosity structure
- Thermoelements (for Thermography)
- Stainless steel-plate for backside reflection calibration
- Plastic tubes (for Radiography)



Plastic tubes

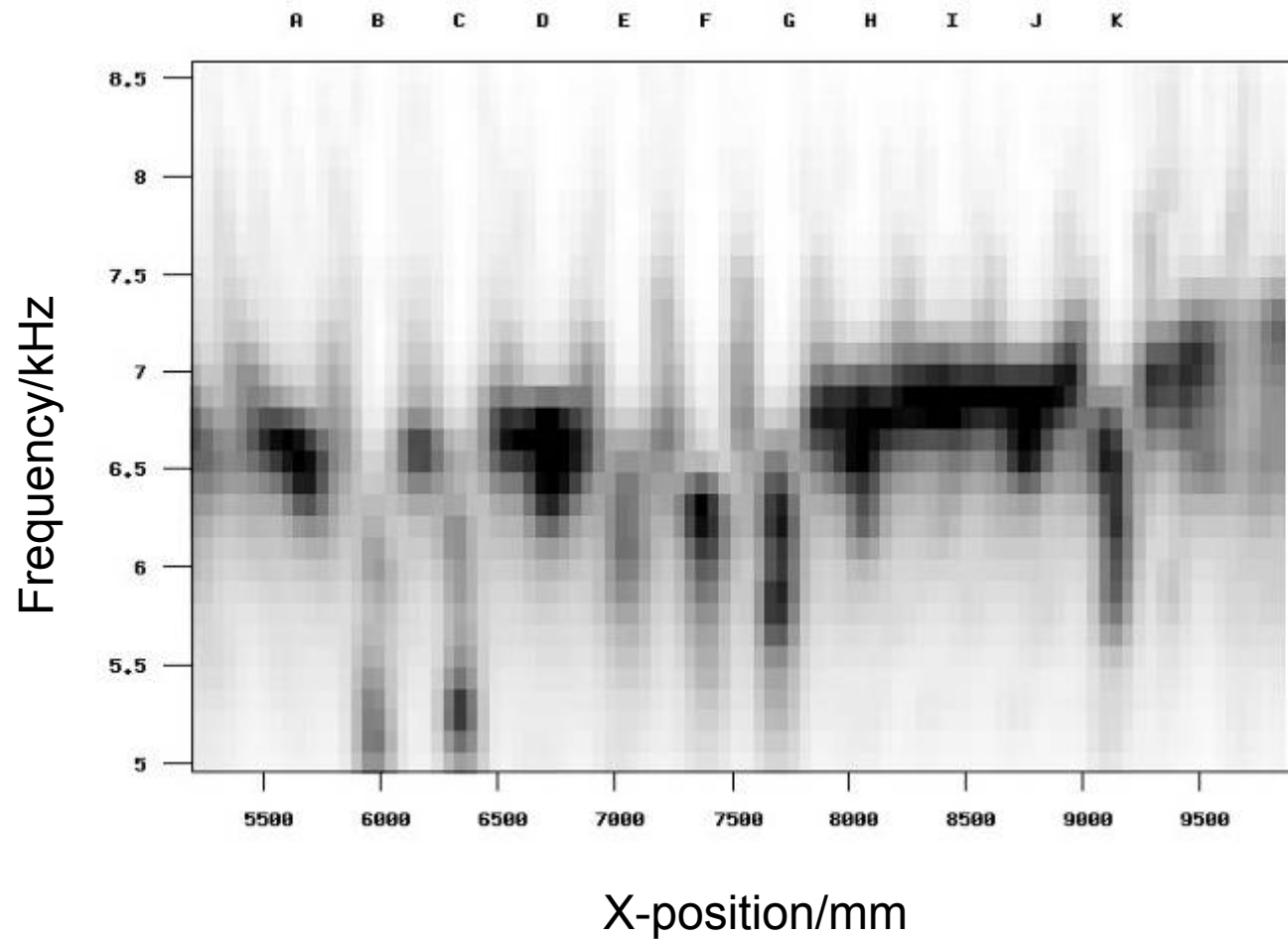


Impact-Echo:
Imaging of apparent
thickness of slab
(C-scan)

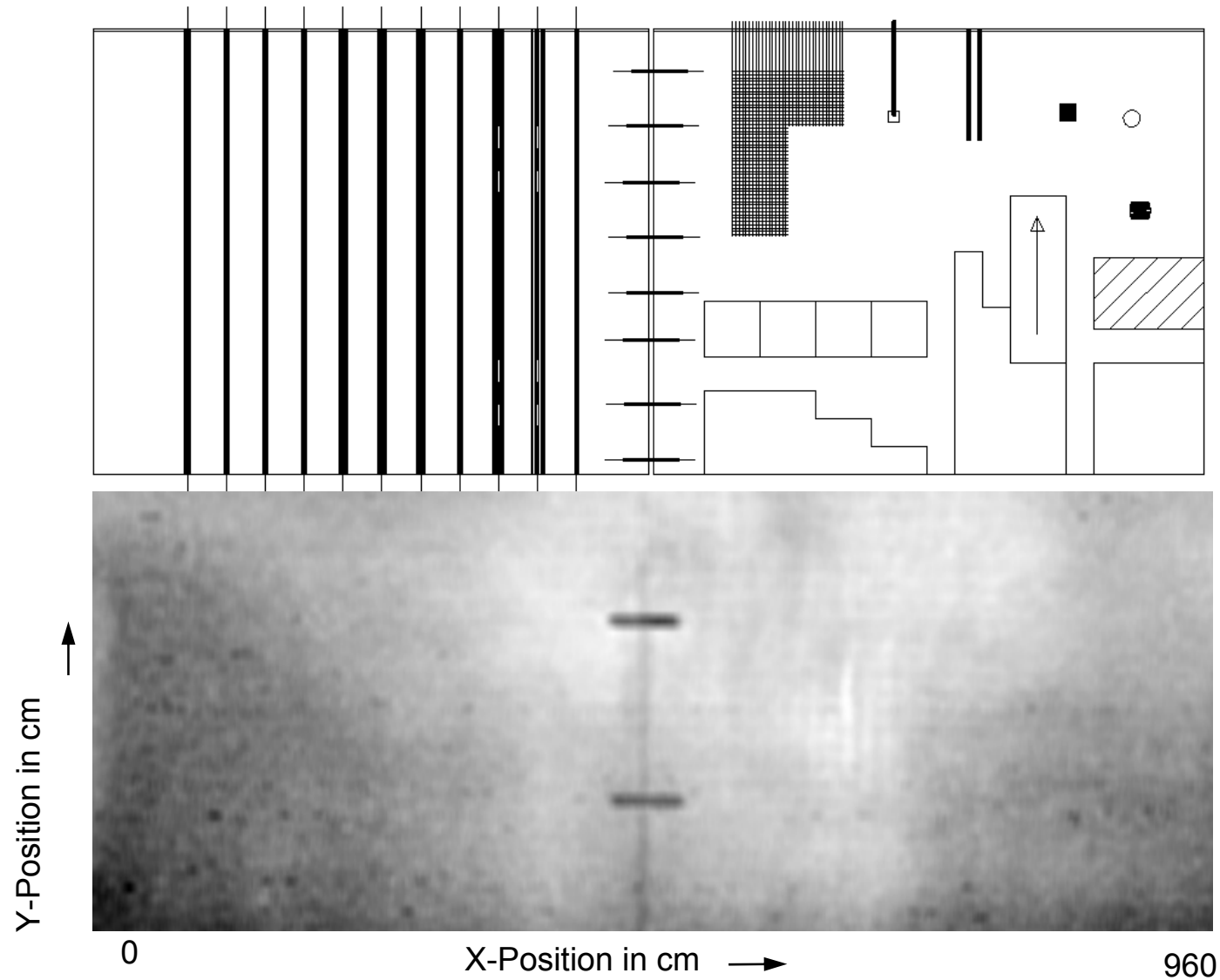
Indirect indication of
grouting defects

Impact-Echo: D-Scan across Ducts

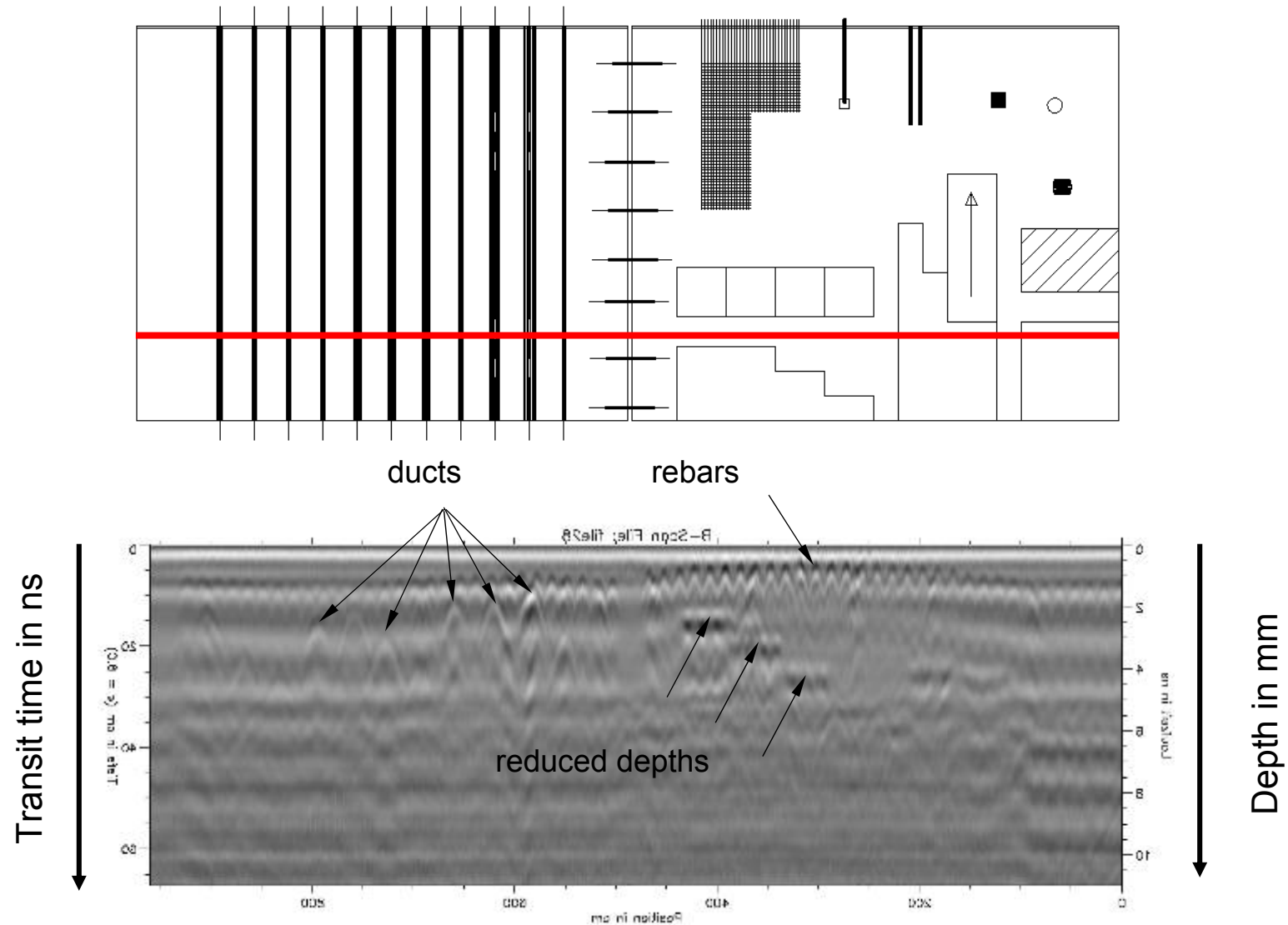
Shifting of back wall echo caused by the tendon ducts



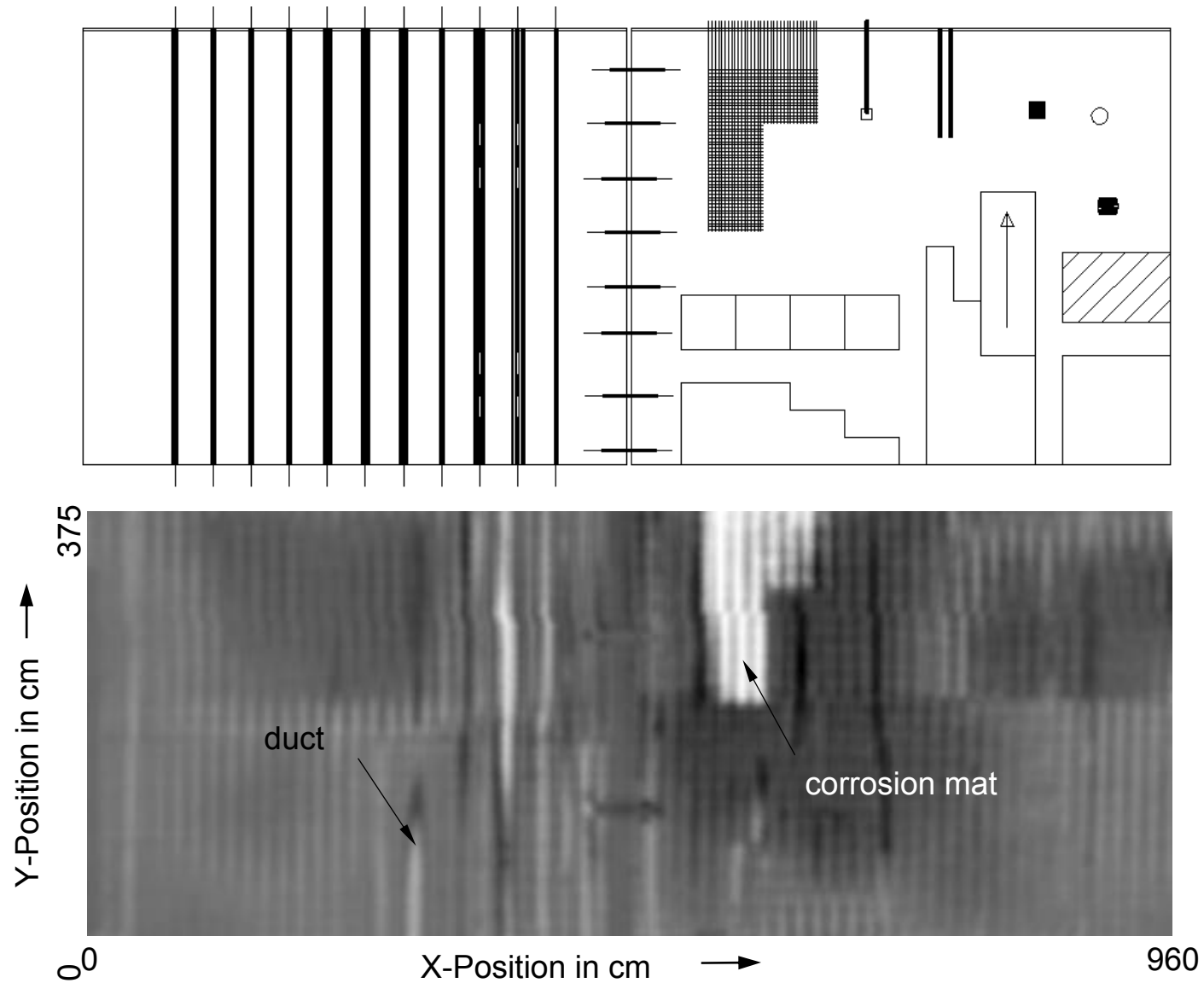
Raw data of GBP (3D)



RADAR: Raw radargram of a long trace



Raw C-scan (depth slice) at a depth of 10 cm



Bridge Examples

Bridge investigations applying NDT-CE



Bridge deck: Full field investigation
8 Measuring field for detailed
investigation with Radar, Ultrasonic
echo, impact-echo, (magnetic stray field)
(1999)



Girder and Bridge deck:
Scanning Echo methods for
tendon ducts and
honeycombing (2001)

New: Large field investigation with automated scanning system for echo
methods (2003)

Application at post-tensioned concrete bridge Large Area Investigation (Scanner)

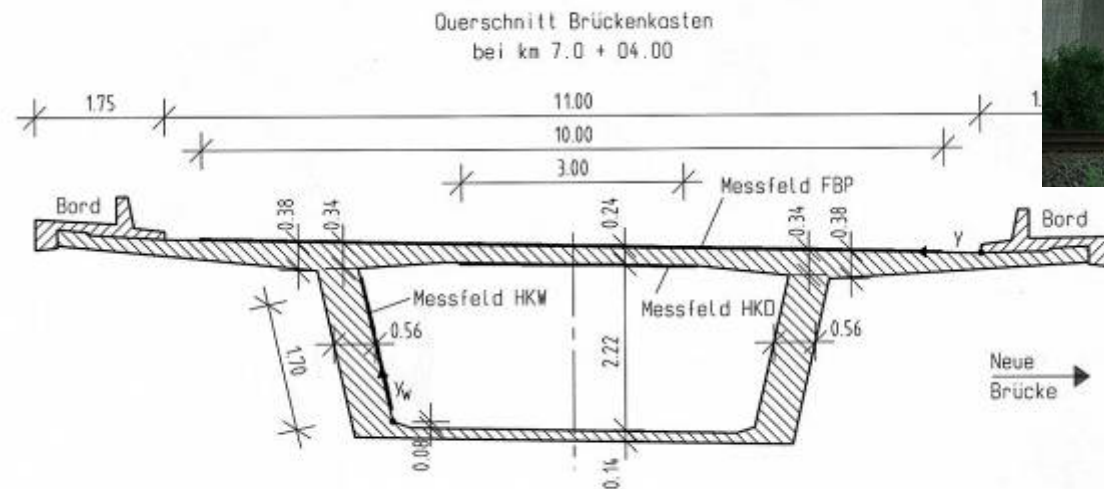
Construction

Cantilever unicellular box bridge

Length: 480 m

Prestressed in longitudinal and transversal direction

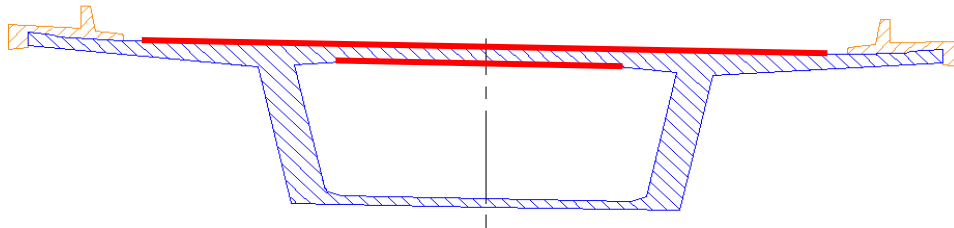
Constructed 1966, deconstruction 2004



- Radar
- Impact-Echo
- Ultrasonic Echo

Results

Measurements on a post-tensioned bridge deck



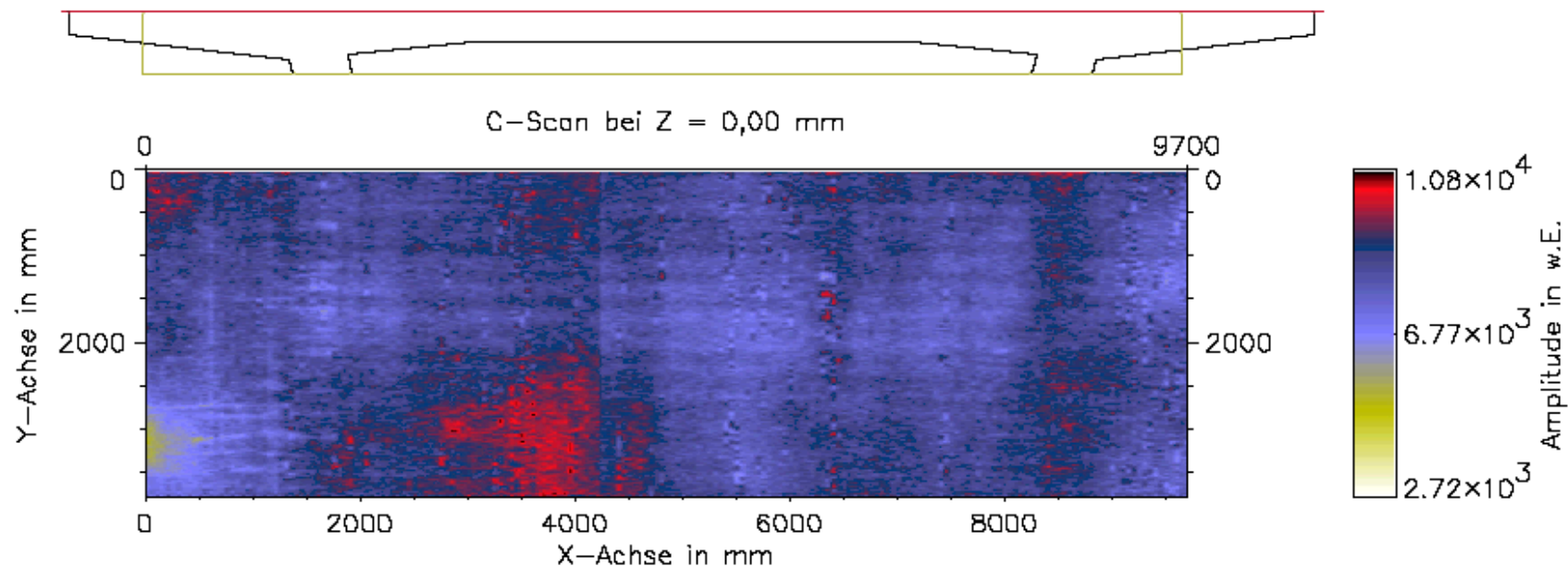
Test Area on the top: 4.0 m x 10.0 m

Test Area on the bottom: 3.0 m x 10.0 m

- tendon ducts with diameters of 45 mm, each with 6 wires
- thickness of the deck 23 - 38 cm

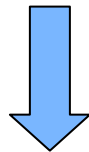


Bridge deck: of radar data from the top side and bottom side Superposition (Polarization in x- und y-direction, maximum of magnitude is represented)
Movie of slices parallel to the surface:

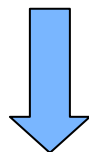


Radar-Visualization of the Results as 3D-Animation

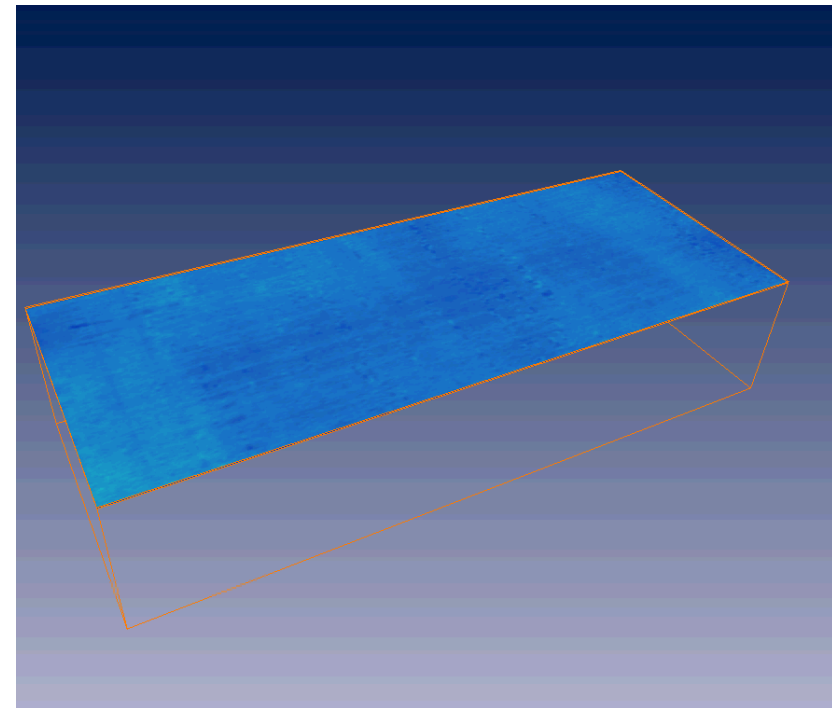
2 Data Sets
recorded with the 1.5 GHz-antenna
with polarization in x and y-direction



3D-Reconstruction with SAFT
(Synthetic Aperture Focusing Technique)



Data Fusion

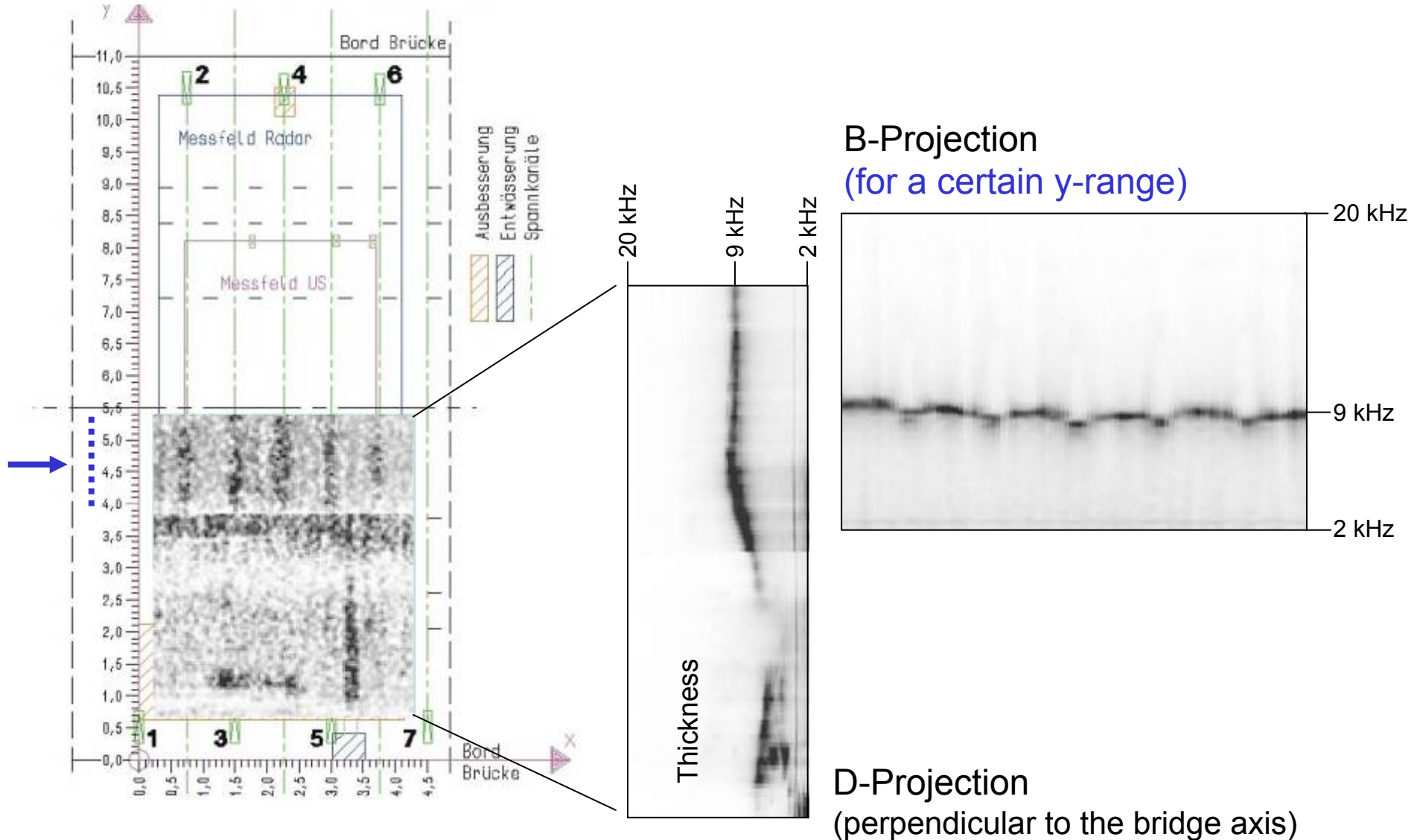


Test Area 4.0 m x 10.0 m



Duct investigation (Impact-Echo)

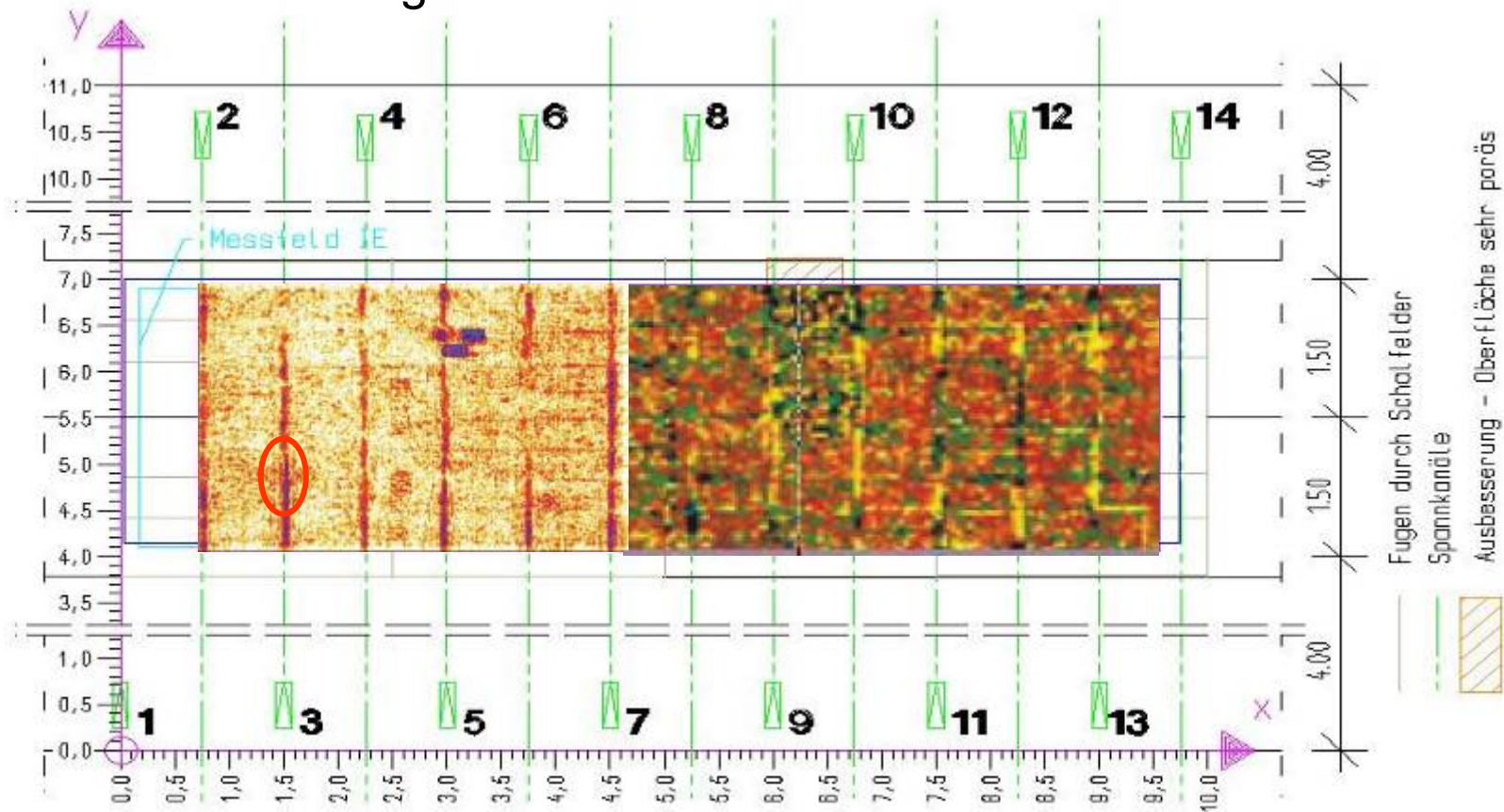
Bridge deck top side: C-Projection close behind the back wall



Ultrasound: Duct investigation



Bridge deck bottom side



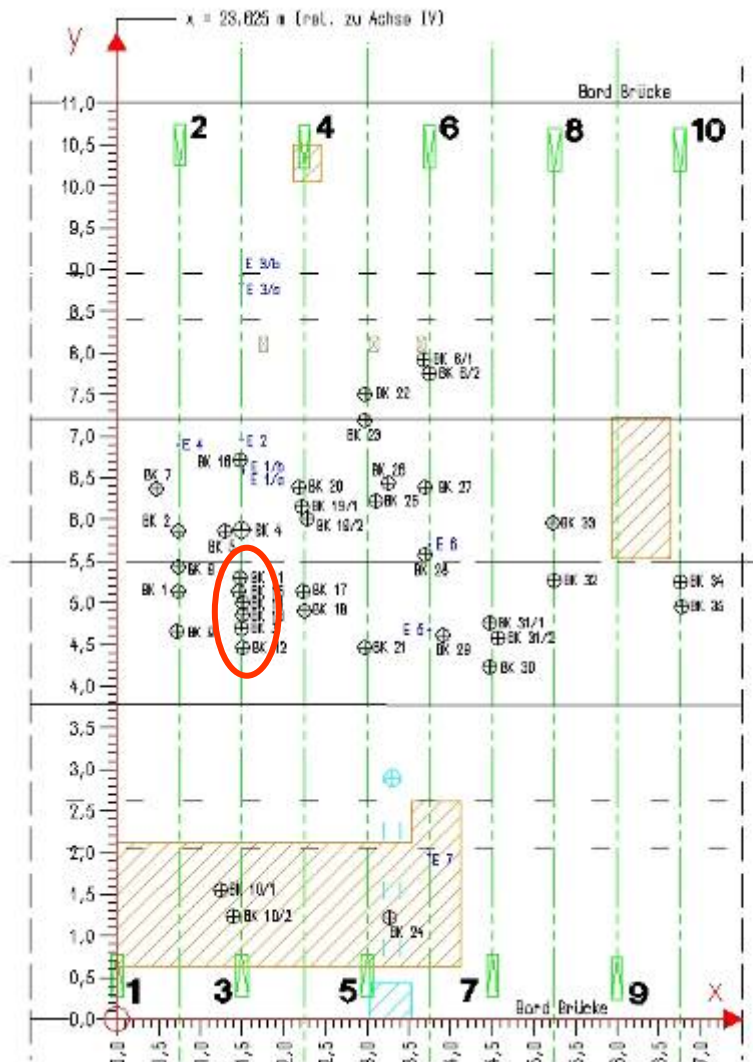
Left:
SAFT-C-Projection
depth 11,7 cm ... 12,1 cm
step width 2,5 cm



High
reflection
intensity at
both sides

Right:
C-scan depth about 8 cm
step width 5 cm

Bridge-deck: Destructiv testing: 35 cores, endoscopy

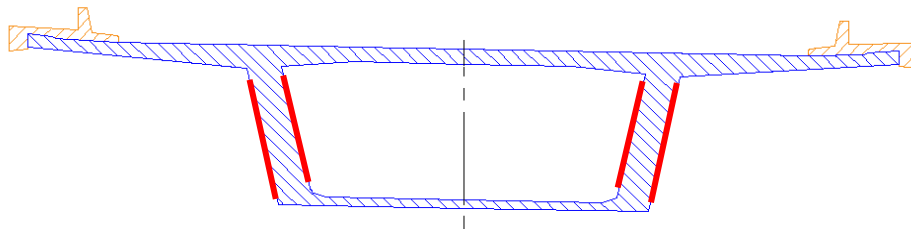


Bridge deck (transverse tendon ducts):
Very good grouting condition



Box girder wall (longitudinal tendon ducts)

Measurements on webs of box girder bridges

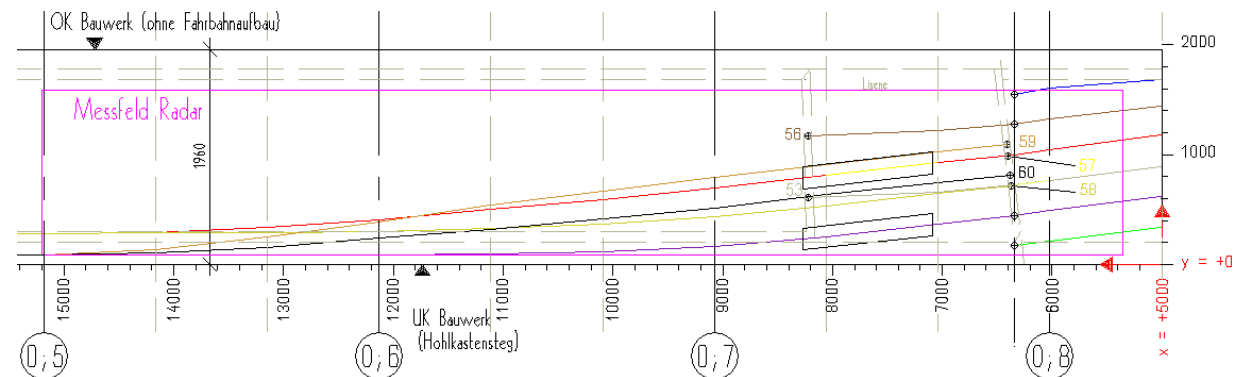


- thickness of the web 50 cm
(83 cm in the area of anchoring of the pre-stressing)

- bridge under unaffected traffic

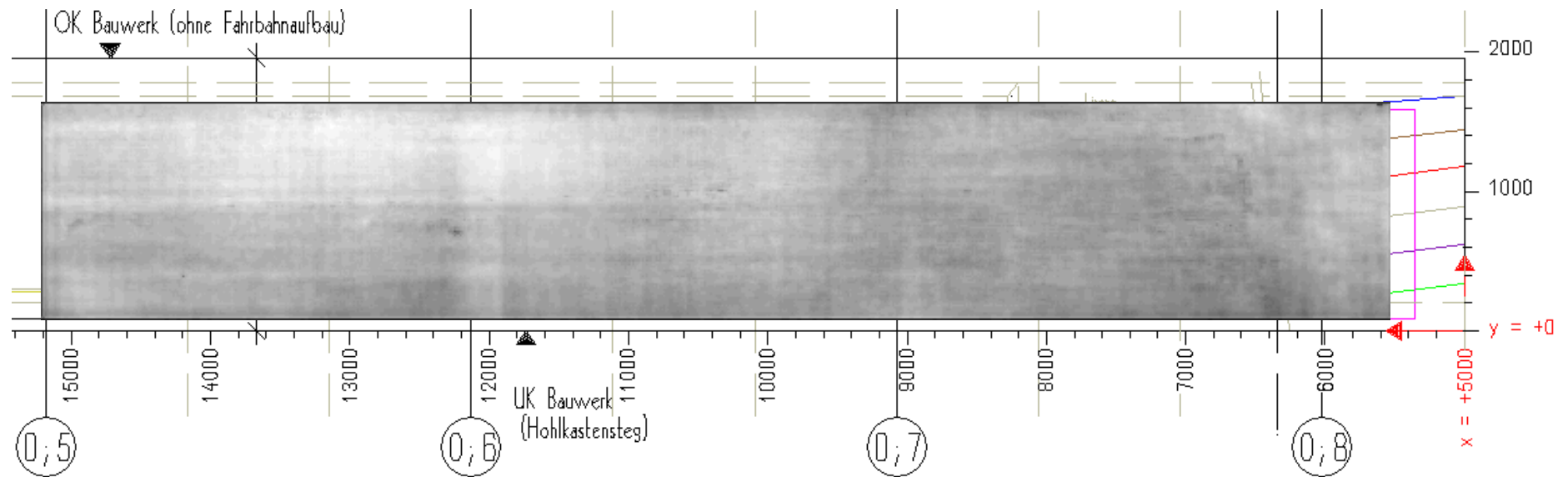
Test Area: 10 m (length) x 1.5 m (height)

- simultaneous mounting of the impact-echo and ultrasonic sensors on the scanner



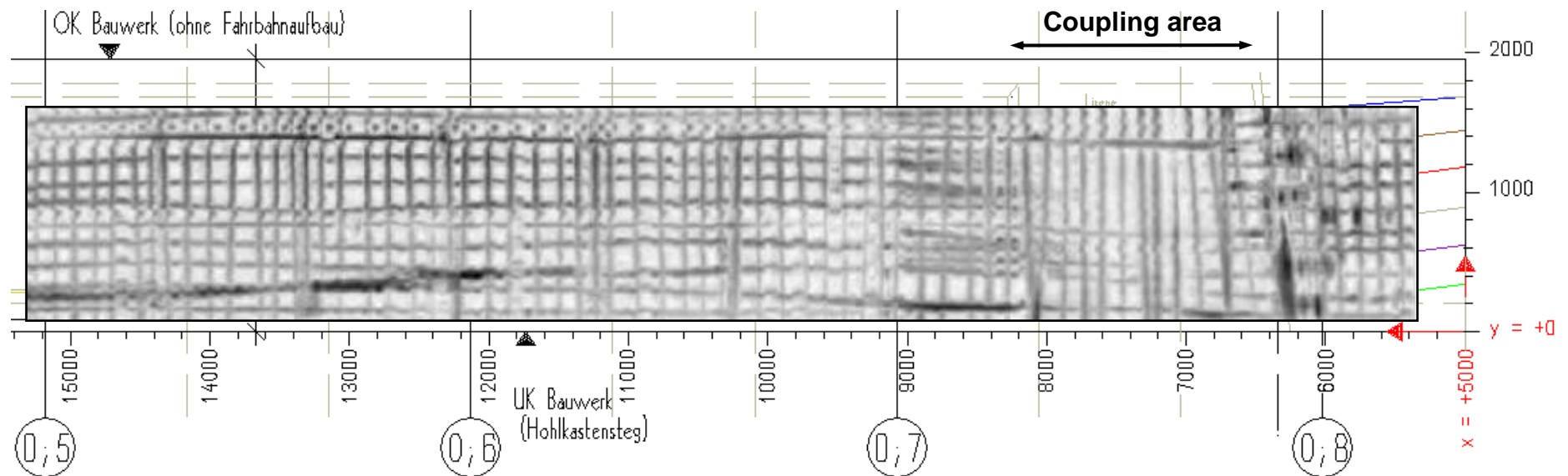
Data Fusion of Radar and Ultrasonic Echo

3D-reconstructed and fused radar data sets (1.5 GHz-antenna) and 3D-reconstructed ultrasonic echo data set



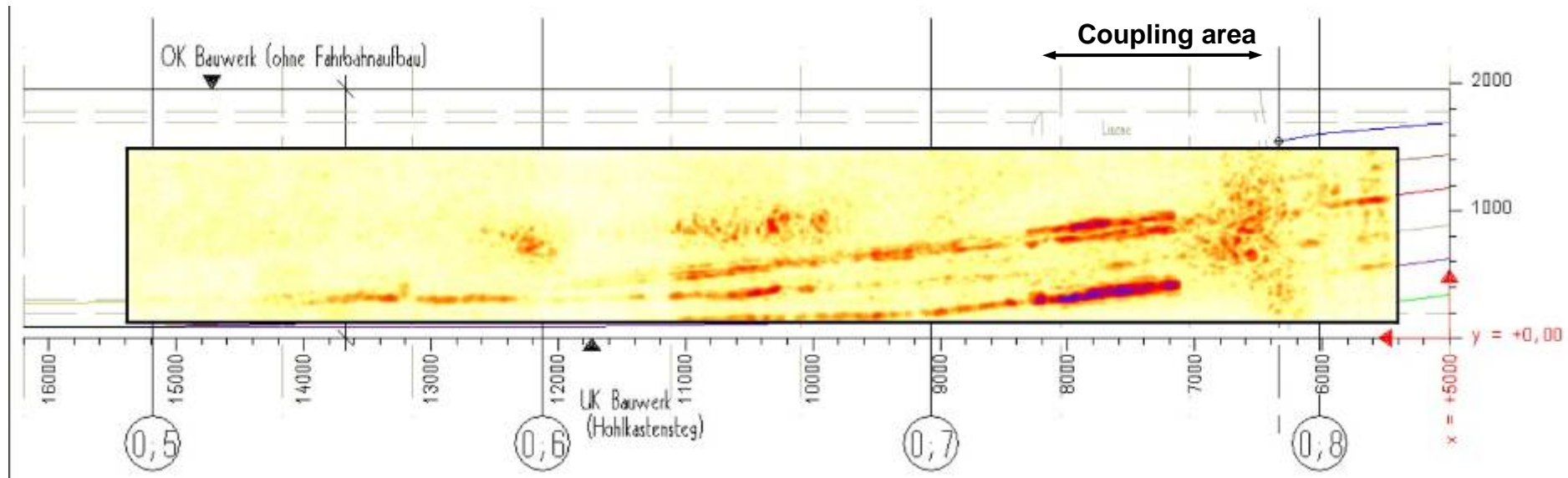
Animated sections parallel to the surface
through the measurement depths from 0 cm to 60 cm

Radar



SAFT-C-Scan parallel to the surface in a measurement depth of 7.5 cm

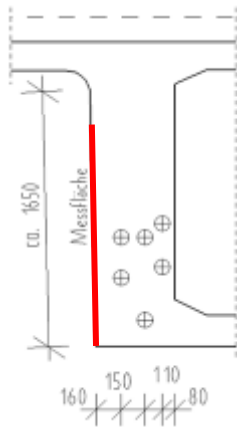
Ultrasonic Echo



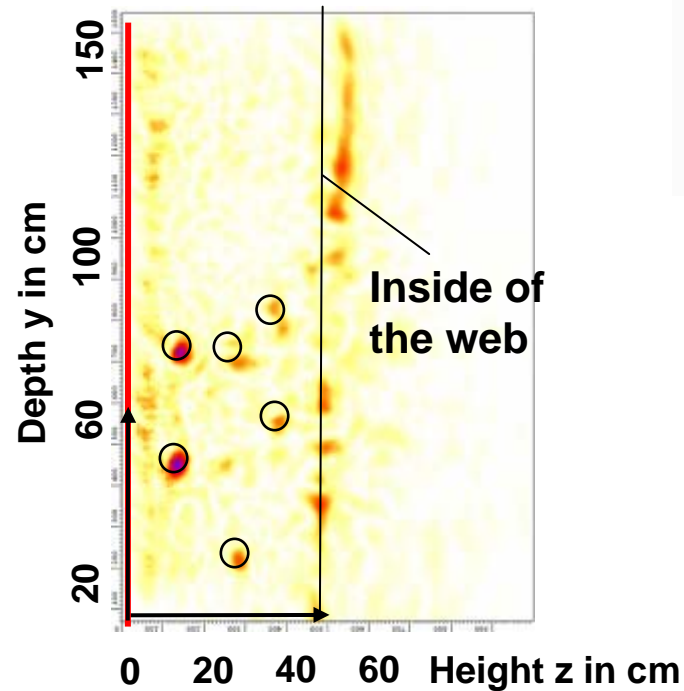
**SAFT-C-Projection parallel to the measurement surface
at the range of depth from 22 cm to 28 cm**

Ultrasonic Echo

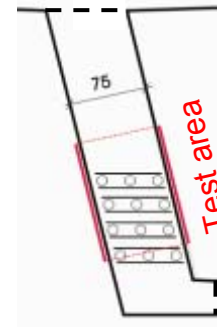
Box girder web
Thickness: 50 cm
Height of test area: 1.40 m



SAFT-B-Scan

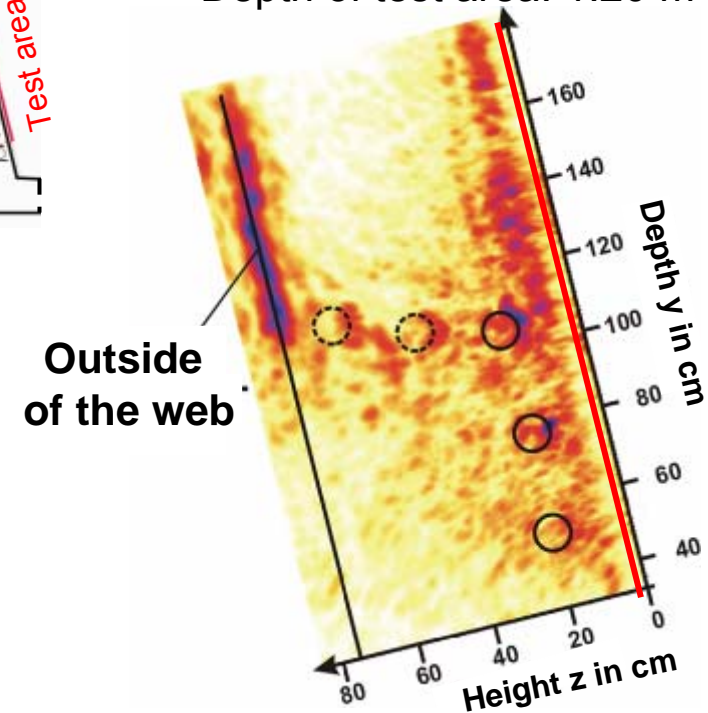


Box girder web
Thickness: 75 cm
Height of test area: 1.60 m



SAFT-B-Projection

Depth of test area: 1.20 m



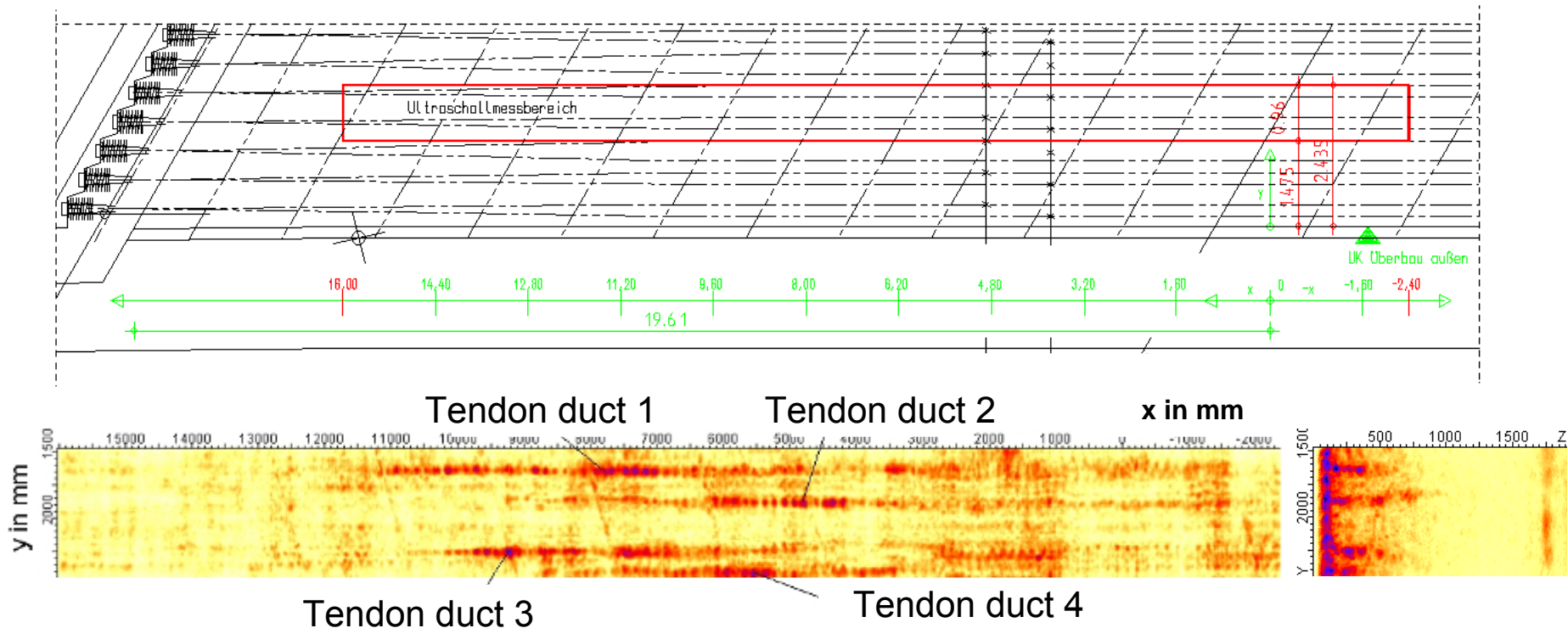
Measurements on a bridge deck, pre-stressed in longitudinal direction

Test Area on the bottom side of the deck, 0.96 m x 18.40 m:

ultrasonic echo measurements were done in 23 scanning areas length of 2 m x 0.40 m



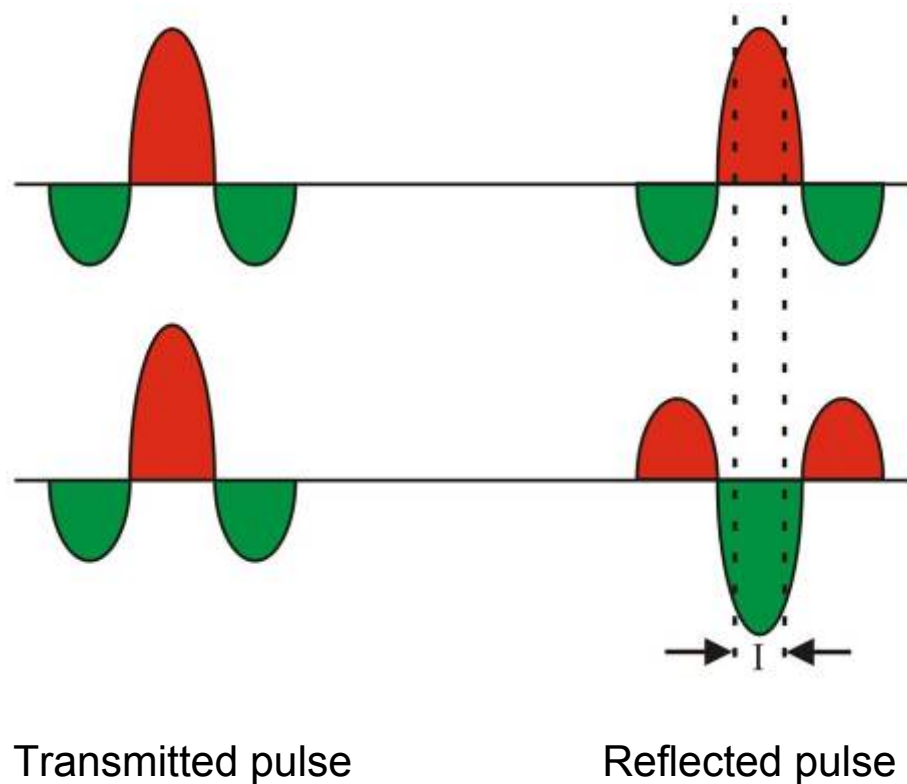
Ultrasonic Echo



SAFT-C-Projection in the depth range of $z = 200 - 400$ mm

Right: SAFT-B-Projection about the whole length of 18.40 m

Pulse Behaviour of Ultrasonic Echo-Signals



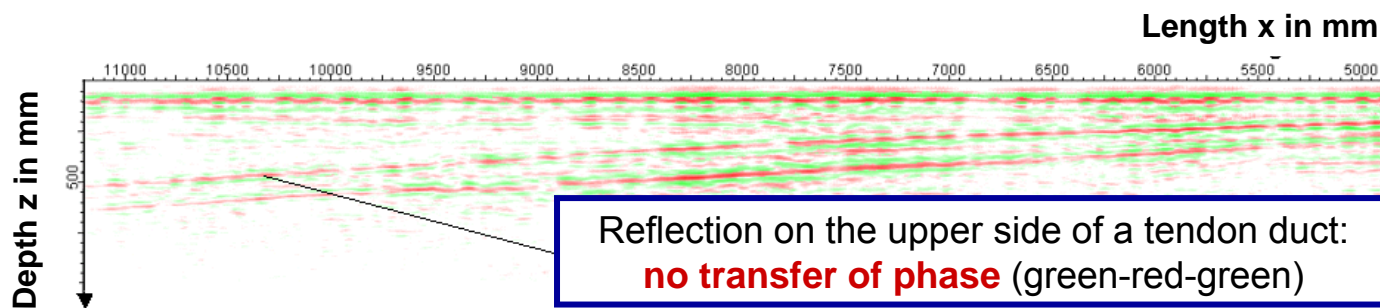
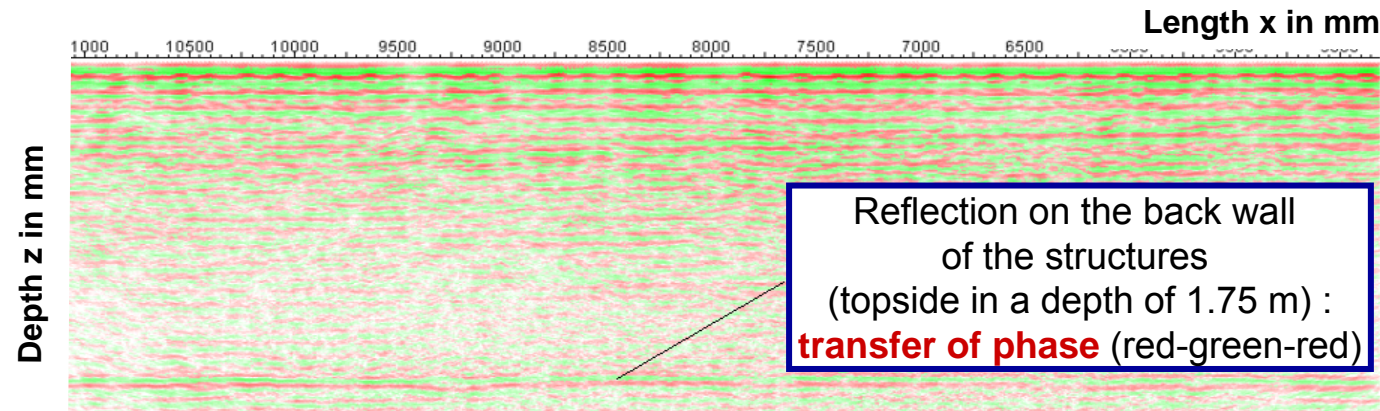
Reflections on steel in concrete

→ **No transfers of phase**

Reflection on air-inclusions in concrete

→ **Transfer of phase**

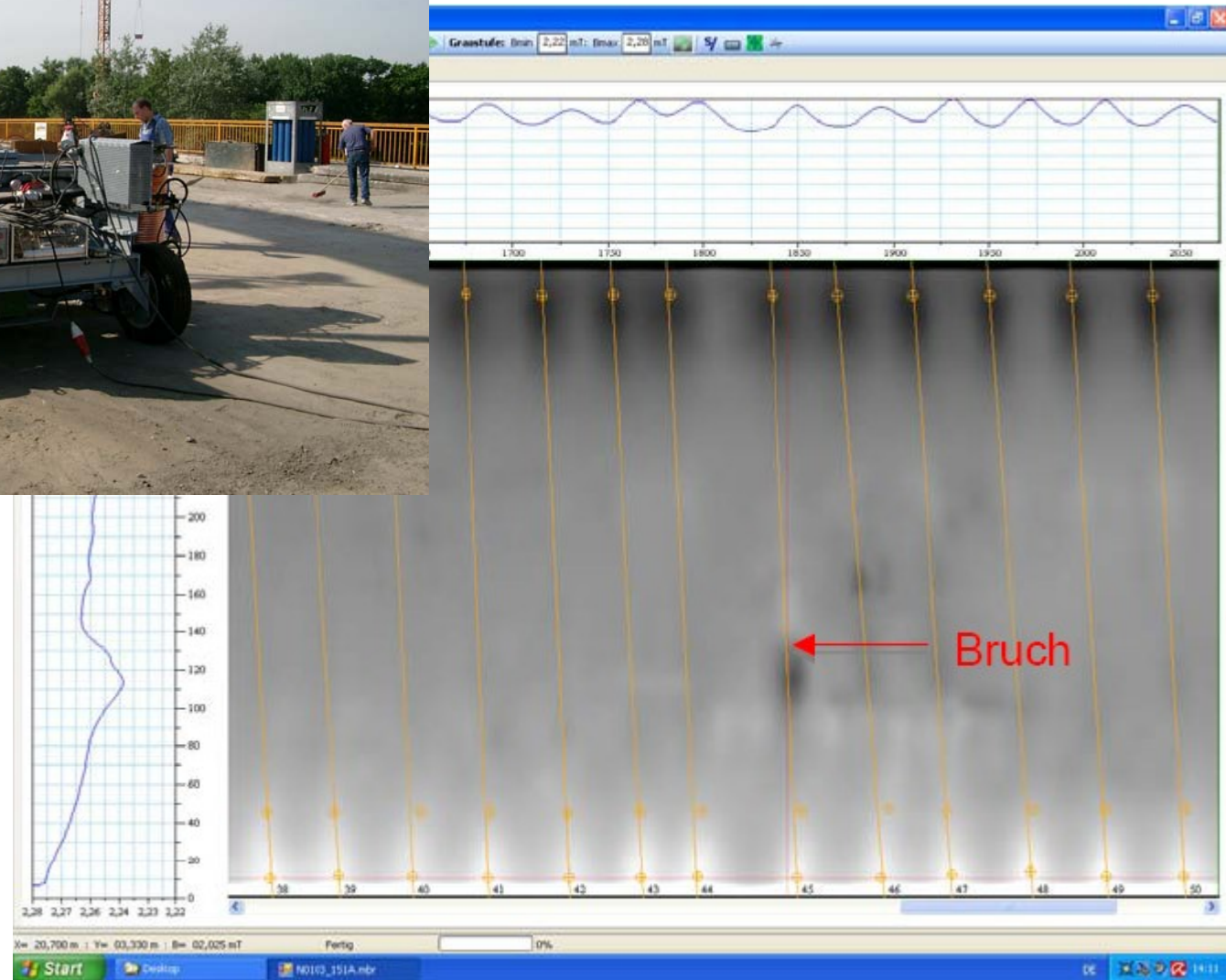
Evaluation of Pulse Behaviour of Ultrasonic Echo-Signals



SAFT-B-Projection (Phase)

Top: about y=1940-2100 mm, Down: about y=1828-1926 mm (tendon duct 2)

Locating tendon cracks in PT Concrete



Scheel, Hillemeier, TUB
Flohrer, HochTief

Conclusions

Automated Measuring system (scanner): Successful application at large concrete slab (LCS) and on bridges

- LCS is very well suited for comparison of test methods
- **RADAR** can localize tendons with high accuracy
- **Ultrasonic echo** (dry contact) can localize ducts and identify grouting defects
- **Impact-echo** gives indirect indication of grouting defects

Successful application at a post-tensioned concrete bridge:

Localization, Concrete Cover
reinforcing rebars, tendon ducts

Condition of tendon ducts

Verification
43 cores, endoscopy

RADAR:

Fast accurate 3D-imaging (Visualization)

- Measuring with high precision

Impact-echo: Large area imaging
and back wall echo shift

Ultrasonic echo: Direct imaging

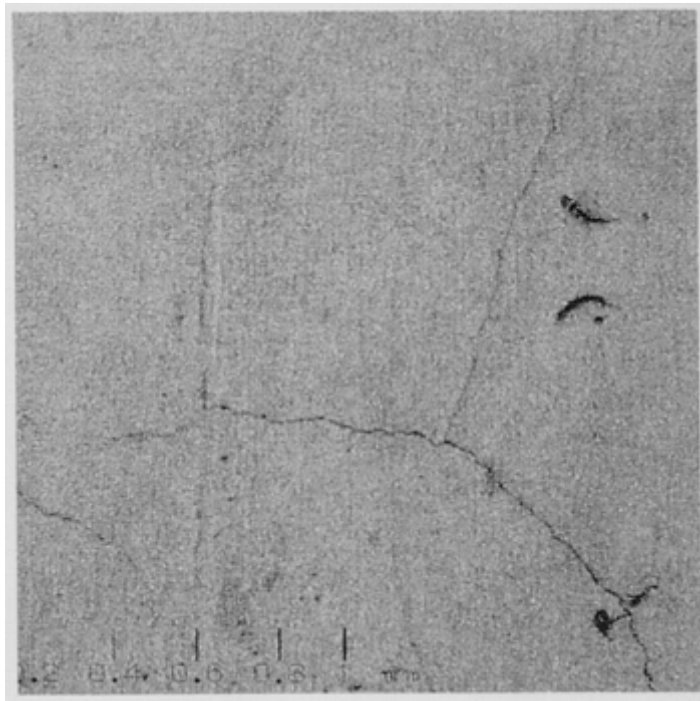
- No clear indication of grouting faults

Confirmation: No grouting fault

What's next?

Robot

- Crack documentation on Metropolitan (1995) Highways Tokyo (View area 2 x 2 m²)





Video on YouTube: BestoScan

Self navigating Robot for horizontal surfaces (Park decks)

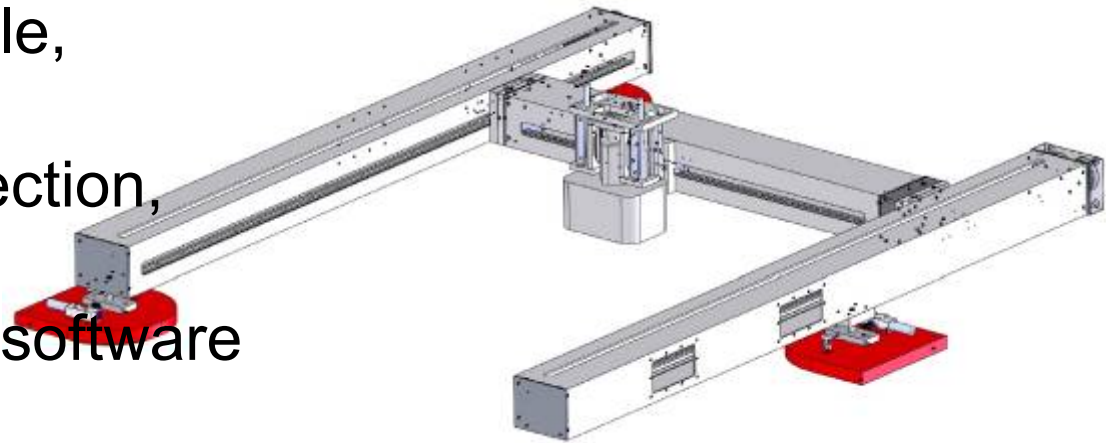
Robot: Possible sensors



Development of the On-Site SCAnner (OSSCAR)

➤ Requirements:

Robust, transportable,
on-site results,
controller, data collection,
data analysis and
presentation in *one* software



➤ Consortium: Integrated project OSSCAR founded by BMWi, Coordinator: BAM



Method combination in OSSCAR



- Synergy by combination of radar, ultrasonic echo and eddy current

Radar



Ultrasonic echo



Eddy current



Suitable for metallic reflectors

Limited penetration depth (young concrete)

Larger penetration depth also in areas with high reinforcement ratio

Limited resolution of single rebars

Measurement of reinforcement diameter

Information only about upper layer

Calibration of radar (ϵ : dielectric constant)

First on-site application



- Bridge close to Frankfurt over the river *Main* (2009-Sep)



Robot

- **Climbing machine equipped with**
 - camera
 - radar
 - impact-echo
 - ...



ROSY climbing machine (Yberle)

Robot



EC Project: Robosense

Thank you for attention !

Vienna City Administration



bast

ASV Fulda

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FOR 384 

Research group
supported by the DFG (Deutsche
Forschungsgemeinschaft)

U N I K A S S E L
V E R S I T Ä T

Die Bahn



BAM Zerstörungsfreie
Schadensdiagnose und
Umweltmessverfahren
VIII.2